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The complexity of sparse Hensel lifting and sparse polynomial factorization

Michael Monagan, Baris Tuncer

Department of Mathematics, Simon Fraser University, Burnaby, British Columbia, V5A 1S6, Canada



ARTICLE INFO

Article history:

Received 23 March 2018

Accepted 21 February 2019

Available online 6 May 2019

Keywords:

Polynomial factorization

Sparse polynomial interpolation

Multivariate Hensel lifting

Polynomial diophantine equations

ABSTRACT

The standard approach to factor a multivariate polynomial in $\mathbb{Z}[x_1, x_2, \dots, x_n]$ is to factor a univariate image in $\mathbb{Z}[x_1]$ then recover the multivariate factors from their univariate images using a process known as multivariate Hensel lifting. Wang's multivariate Hensel lifting recovers the variables one at a time. It is currently implemented in many computer algebra systems, including Maple, Magma and Singular.

When the factors are sparse, Wang's approach can be exponential in the number of variables n . To address this, sparse Hensel lifting was introduced by Zippel and then improved by Kaltofen. Recently, Monagan and Tuncer introduced a new approach which uses sparse polynomial interpolation to solve the multivariate polynomial diophantine equations that arise inside Hensel lifting in random polynomial time. This approach is shown to be practical and faster than Zippel's and Kaltofen's algorithms and faster than Wang's algorithm for non-zero evaluation points. In this work we first present a complete description of the sparse interpolation used by Monagan and Tuncer and show that it runs in random polynomial time. Next we study what happens to the sparsity of multivariate polynomials when the variables are successively evaluated at numbers. We determine the expected number of remaining terms. We use this result to revisit and correct the complexity analysis of Zippel's original sparse interpolation. Next we present an average case complexity analysis of our approach. We have implemented our algorithm in Maple with some sub-algorithms implemented in C. We present some experimental data comparing our approach with Wang's method for both sparse and dense factors. The data shows that our method is always

E-mail addresses: mmonagan@cecm.sfu.ca (M. Monagan), ytuncer@sfu.ca (B. Tuncer).

<https://doi.org/10.1016/j.jsc.2019.05.001>

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competitive with Wang's method and faster when Wang's method is exponential in n .

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1. Introduction

Suppose we seek to factor a multivariate polynomial $a \in \mathbb{Z}[x_1, \dots, x_n]$. We first choose a main variable, say x_1 , and compute the content of a in x_1 and remove it from a . Here, if $a = \sum_{i=0}^d a_i(x_2, \dots, x_n)x_1^i$, the content of a in x_1 is $\gcd(a_0, a_1, \dots, a_d)$, a polynomial in one fewer variables which is factored recursively. Let us assume this has been done.

The second step identifies any repeated factors in a by doing a *square-free factorization*. See Ch. 8 of Geddes et al. (1992). In this step one obtains the factorization $a = b_1 b_2^2 b_3^3 \dots b_k^k$ such that each factor b_i has no repeated factors and $\gcd(b_i, b_j) = 1$. Let us assume this has also been done. So let $a = f_1 f_2 \dots f_m$ be the irreducible factorization of a over \mathbb{Z} .

The multivariate Hensel lifting algorithm (MHL) developed by Yun (1974) and improved by Wang (1978, 1975) chooses an evaluation point $\alpha = (\alpha_2, \alpha_3, \dots, \alpha_n) \in \mathbb{Z}^{n-1}$ and factors the univariate image $a(x_1, \alpha_2, \dots, \alpha_n)$ over \mathbb{Z} . The evaluation point must satisfy

- (i) $L(\alpha_2, \dots, \alpha_n) \neq 0$ where L is the leading coefficient of a in x_1 ,
- (ii) $a(x_1, \alpha_2, \dots, \alpha_n)$ must have no repeated factors in x_1 and
- (iii) $f_i(x_1, \alpha_2, \dots, \alpha_n)$ must be irreducible over \mathbb{Q} .

If any condition is not satisfied the algorithm must restart with a new evaluation point. Conditions (i) and (ii) may be imposed in advance of the next step. To ensure that condition (iii) is true with high probability Maple picks a second random evaluation point $\beta = (\beta_2, \dots, \beta_n) \in \mathbb{Z}^{n-1}$, factors $a(x_1, \beta_2, \dots, \beta_n)$ over \mathbb{Z} and checks that the two factorizations have the same degree pattern before proceeding.

For simplicity let us assume a is monic in x_1 and $a = fg$. Suppose we have obtained the monic factors $f(x_1, \alpha_2, \dots, \alpha_n)$ and $g(x_1, \alpha_2, \dots, \alpha_n)$ in $\mathbb{Z}[x_1]$. Next the algorithm picks a prime p for Hensel lifting.¹ For a given polynomial $h \in \mathbb{Z}[x_1, \dots, x_n]$, let us use the notation

$$h_j := h(x_1, \dots, x_j, x_{j+1} = \alpha_{j+1}, \dots, x_n = \alpha_n) \bmod p$$

so that $a_1 = a(x_1, \alpha_2, \dots, \alpha_n) \bmod p$. The input to MHL is a, α, f_1, g_1 and p such that $a_1 = f_1 g_1$ and $\gcd(f_1, g_1) = 1$ in $\mathbb{Z}_p[x_1]$. If the condition $\gcd(f_1, g_1) = 1$ is not satisfied, the algorithm chooses a new prime p until it is.

Wang's MHL lifts the factors f_1, g_1 to f_2, g_2 then to f_3, g_3 , etc., until we obtain f_n, g_n . That is, Wang's MHL recovers the variables in the factors one at a time. After MHL, assuming (iii) holds, we have $f_n = f \bmod p$ and $g_n = g \bmod p$. Therefore, for p sufficiently large, we recover the factorization $a = fg$ over \mathbb{Z} .

We give a brief description here of the j th step of MHL for $j > 1$. For details see Ch. 6 of Geddes et al. (1992). The input is a_j, f_{j-1}, g_{j-1} and the output is f_j, g_j satisfying $a_j = f_j g_j$. There are two main subroutines in the design of MHL. The first one is the leading coefficient correction algorithm (LCC). The most well-known is the Wang's heuristic LCC (Wang and Rothschild, 1975) which works well in practice and is the one Maple currently uses. For details of Wang's LCC method and examples see Tuncer (2017). There are other approaches by Kaltofen (1985) and most recently by Lee (2013). In our implementation we use Wang's LCC.

¹ One may also perform Hensel lifting modulo a power of a prime instead of a large prime – see Ch. 6 of Geddes et al. (1992). Our methods may also be done modulo a power of a prime but we omit the details here.

In a typical application of Wang’s LCC, one first factors the leading coefficient of a , a polynomial in $\mathbb{Z}[x_2, \dots, x_n]$, then one applies LCC before the j th step of MHL. Then the total cost of the factorization of $a(x_1, x_2, \dots, x_n)$ is given by the cost of LCC + the cost of factoring $a(x_1, \alpha_2, \dots, \alpha_n)$ over \mathbb{Z} + the cost of MHL. One can easily construct examples where LCC or factoring $a(x_1, \alpha_2, \dots, \alpha_n)$ dominates the cost. However this is not typical. Typically, MHL dominates the cost.

The second main subroutine solves a multivariate polynomial diophantine problem (MDP). In MHL, for each j with $2 \leq j \leq n$, Wang’s design of MHL must solve many MDP instances in $\mathbb{Z}_p[x_1, \dots, x_{j-1}]$. See Step 6 of Algorithm 1. In the Maple timings in Section 8, we will show that often 80% or more is spent solving MDPs. Wang’s method for solving an MDP (see Algorithm 2) is recursive. It is exponential in n for sparse factors when the evaluation points $\alpha_2, \dots, \alpha_n$ are non-zero. Tables 10 and 11 illustrate this. To solve this problem, sparse Hensel lifting (SHL) was introduced by Zippel (1981) and then improved by Kaltofen (1985). In Monagan and Tuncer (2016b) we proposed various approaches of sparse interpolation to solve MDP and presented our version of SHL. We also compared our SHL with Kaltofen’s SHL in Kaltofen (1985).

In this paper we assume a, f, g are monic in x_1 so as not to complicate the presentation of SHL algorithm with LCC. In Section 2 we define the MDP in detail and show that interpolation is an option to solve the MDP. If the factors to be computed are sparse then the solutions to the MDP are also sparse. Then we present Algorithm 4 which uses Zippel’s sparse interpolation from Zippel (1990) to solve the MDP. Section 2 also describes the multivariate polynomial evaluation method that we use because evaluation is often the most expensive part of our SHL.

In Section 3 we will give the idea of SHL and our organization of SHL which is presented as Algorithm 5 MTSHL. In Appendix A we give a concrete example of how the j th step of MTSHL works. Algorithm 4 SparseInterpolate shows how we solve the MDP using sparse interpolation. Since Algorithm 4 is probabilistic we bound the probability that it may fail (see Proposition 3).

The cost of the j th step of MHL (Algorithm 1) depends on the degree and number of terms of a_j and the factors f_j and g_j being computed. Let $\#h$ and also T_h denote the number of terms of a polynomial h . In Section 4 we study what happens to a when we successively evaluate it at non-zero numbers, that is, we are interested in the sequence $\#a_n, \#a_{n-1}, \dots, \#a_1$. A simple experiment will show what happens when a is sparse. The Maple command `randpoly` below constructs a sparse polynomial with 10,000 terms with monomials chosen uniformly at random from the set of all monomials in (x_1, \dots, x_{12}) with total degree at most 15 and with integer coefficients chosen from $[1, 99]$ uniformly at random.

```
> X := [x1, x2, x3, x4, x, x6, x7, x8, x9, x10, x11, x12];
> a := randpoly(X, degree=15, terms=10000, coeffs=rand(1..99));
```

We obtain the following data using $(\alpha_2, \alpha_3, \dots, \alpha_{12}) = (3, 5, 2, 7, 9, 1, 6, 2, 4, 5, 7)$.

j	12	11	10	9	8	7	6	5	4	3	2	1
$\#a_j$	10000	9996	9954	9802	9207	7550	4837	2478	978	304	68	12

The reader should observe that the number of terms does not drop significantly until we have evaluated about half of the variables. This means that the cost of recovering x_7, x_8, \dots, x_{11} with Hensel lifting is not significantly cheaper than recovering x_{12} . In Section 4 we determine the expected value of the $\#a_i$ and make this observation precise. The observations in Section 4 show that one of the assumptions made by Zippel in his complexity analysis of sparse interpolation in Zippel (1979) is false. We will revise this assumption and correct his analysis.

In the j th step of MHL we recover x_j in the factors f_j and g_j . Let

$$f_j = \sum_{i=0}^{\deg(f_j, x_j)} \sigma_i(x_j - \alpha_j)^i \text{ and } g_j = \sum_{i=0}^{\deg(g_j, x_j)} \tau_i(x_j - \alpha_j)^i$$

where $\sigma_i, \tau_i \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$. These are the Taylor polynomials for f_j and g_j expanded about $x_j = \alpha_j$. Let $\text{Supp}(f)$ denote the support of f , that is, the set of monomials of f . For example if we expand $f = x^3 - xyz^2 + y^3z^2 + z^3 - 27$ about $z=2$ we get

$$f = \underbrace{(x^3 + 4y^3 - 4xy - 19)}_{\sigma_0} + \underbrace{(4y^3 - 4xy + 12)}_{\sigma_1}(z - 2) + \underbrace{(y^3 - xy + 6)}_{\sigma_2}(z - 2)^2 + \underbrace{1}_{\sigma_3}(z - 2)^4$$

Thus $\text{Supp}(\sigma_0) = \{x^3, y^3, xy, 1\}$, $\text{Supp}(\sigma_1) = \text{Supp}(\sigma_2) = \{y^3, xy, 1\}$, and $\text{Supp}(\sigma_3) = \{1\}$. Algorithm 1 and Algorithm 5 first compute f_{j-1} and g_{j-1} recursively and initialize $\sigma_0 := f_{j-1}$ and $\tau_0 := g_{j-1}$. Then, for $k = 1, 2, \dots$, they compute (σ_k, τ_k) by solving the MDP $\sigma_k g_{j-1} + \tau_k f_{j-1} = c_k$ where c_k is the Taylor coefficient

$$\text{coeff}(a_j - \left(\sum_{i=0}^{k-1} \sigma_i(x_j - \alpha_j)^i\right) \left(\sum_{i=0}^{k-1} \tau_i(x_j - \alpha_j)^i\right), (x_j - \alpha_j)^k).$$

We make three observations about the coefficients σ_i and τ_i . Recall that the Taylor coefficient σ_i is given by the formula $f_j^{(i)}(\alpha_j)/i!$ where $f_j^{(i)}$ the i th derivative of f_j in x_j . Since $\#f_j^{(i)} \leq \#f_j$ it follows that $\#\sigma_i \leq \#f_j \leq \#f$. Thus if the factors f and g are sparse then the σ_i and τ_i computed during Hensel lifting remain sparse. Secondly, if $\alpha_j \neq 0$, normally

$$\text{Supp}(\sigma_i) \supseteq \text{Supp}(\sigma_{i+1}) \text{ for } 0 \leq i < \text{deg}(f_j, x_j).$$

This is the key property that forms the basis for Algorithm 5 (MTSHL). The reader may verify this holds for the example where $\alpha=2$ but it does not hold if $\alpha=0$ or if $\alpha=3$. In Section 3 we show that this property holds for most α_j (see Lemma 1). Algorithm 5 exploits this property by using $\text{Supp}(\sigma_{i-1})$ as the support for σ_i to construct a linear system to solve for the coefficients of σ_i .

Thirdly, because the cost of MHL depends on $|\text{Supp}(\sigma_i)|$ we are interested in the sequence $\#\sigma_i$ for $i = 0, 1, 2, \dots$. To see what happens, let f be the polynomial a above with 10,000 terms and let $f = \sum_{i=0}^{11} \sigma_i(x_{12} - 7)^i$. We obtain the following data for $\#\sigma_i$.

i	0	1	2	3	4	5	6	7	8	9	10	11
$\#\sigma_i$	9996	5526	2988	1504	760	343	158	60	28	8	3	1

What is immediately apparent is that the $\#\sigma_i$ are decreasing rapidly and therefore it will be advantageous if the cost of computing σ_i depends on $\#\sigma_{i-1}$ and not $\#\sigma_0$. In Section 5 we will determine the expected value of $\#\sigma_i$ from which we are able to determine the expected cost of Algorithm 5 (MTSHL) in Sections 6 and 7.

In Section 8 we give some timing data to compare Algorithm 5 with Wang’s factorization algorithm as it is implemented in Maple. We also include some timings for Magma and Singular’s factorization codes which also use Wang’s algorithm to provide some perspective. Finally in Section 9 we briefly comment on what must be done when the input polynomial a has more than two factors.

We end our introduction with further details about multivariate Hensel lifting (MHL). MHL was originally developed to factor polynomials. It can also be applied to compute polynomial greatest common divisors. Given two polynomials a and b in $\mathbb{Z}[x_1, \dots, x_n]$ suppose we want to compute $g = \text{gcd}(a, b)$. If we let $c = a/g$ and $d = b/g$ so that $a = gc$ and $b = gd$, we may apply Hensel lifting to either factorization $a = gc$ or $b = gd$. As in polynomial factorization we choose an evaluation point $\alpha = (\alpha_2, \dots, \alpha_n) \in \mathbb{Z}^{n-1}$ and a prime p which must satisfy certain conditions. We then compute the univariate image $g_1 = \text{gcd}(a(x_1, \alpha_2, \dots, \alpha_n), b(x_1, \alpha_2, \dots, \alpha_n))$ in $\mathbb{Z}[x_1]$. If we use the factorization $a = gc$ then we compute $c_1 = a_1/g_1$ and input a, α, g_1, c_1 and p to MHL. Moses and Yun (1973) were the first to try this. They called their algorithm the EZ-GCD algorithm. For details we refer the reader to Section 7.6 of Geddes et al. (1992).

Why is Hensel lifting done modulo a prime p and not over \mathbb{Z} ? If it were run over \mathbb{Z} , an expression swell occurs in MHL when solving univariate polynomial diophantine equations $\sigma A + \tau B = C$ in $\mathbb{Z}[x]$. Here one first solves $SA + TB = \gcd(A, B) = 1$ for $S, T \in \mathbb{Q}[x_1]$ using the Euclidean algorithm. The denominators in S and T may be as large as the resultant of A and B which is an integer of length approximately $\max(\deg A, \deg B)$ times longer than the integers in A and B . Working modulo a prime p eliminates this expression swell.

How big must the prime p be? Let $\|f\|$ denote the height (maximum of the absolute value of the coefficients) of a polynomial f . If f is an irreducible factor of a over \mathbb{Z} then the prime p used in MHL must satisfy $p > 2\|f\|$ to recover both positive and negative coefficients of f . It is possible that $\|f\| > \|a\|$. For example, the polynomial $x^{105} - y^{105}$ has height 1 but it has a degree 60 reducible factor with height 74 and a degree 48 irreducible factor of height 2. For this purpose the following bound may be derived from Lemma II on page 135 of Gelfond (1952): If f is any factor of a then $\|f\| < e^{d_1+d_2+\dots+d_n} \|a\|$ where $e = 2.7818$ and $d_i = \deg(a, x_i)$.

For factors with large integer coefficients, instead of doing Hensel lifting modulo a large prime p which would require expensive multi-precision arithmetic, one may first perform Hensel lifting modulo a machine prime p then do a p -adic lift to recover the integer coefficients of the factors. The p -adic lift leads to MDPs in $\mathbb{Z}_p[x_1, \dots, x_n]$ where our efficient MDP solver is helpful. For details of this approach see Monagan and Tuncer (2018).

2. The Multivariate Diophantine Problem (MDP)

Following the notation in Section 1, let $u, w, c \in \mathbb{Z}_p[x_1, \dots, x_j]$ with u and w monic with respect to the variable x_1 . Let $\alpha = (\alpha_2, \dots, \alpha_n) \in \mathbb{Z}^{n-1}$ and let $I_j = \langle x_2 - \alpha_2, \dots, x_j - \alpha_j \rangle$ be an ideal of $\mathbb{Z}_p[x_1, \dots, x_j]$. The multivariate diophantine problem (MDP) is to find multivariate polynomials $\sigma, \tau \in \mathbb{Z}_p[x_1, \dots, x_j]$ that satisfy

$$\sigma u + \tau w = c \pmod{I_j^{d_j+1}} \tag{1}$$

with $\deg(\sigma, x_1) < \deg(w, x_1)$ where d_j is the maximal degree of σ and τ with respect to the variables x_2, \dots, x_j and it is given that

$$\text{GCD}(u \pmod{I_j}, w \pmod{I_j}) = 1 \text{ in } \mathbb{Z}_p[x_1].$$

It can be shown that a solution (σ, τ) with $\deg(\sigma, x_1) < \deg(w, x_1)$ exists and is unique and independent of the choice of the ideal I_j . Moreover if $\deg(c, x_1) < \deg(u, x_1) + \deg(w, x_1)$ this solution also satisfies $\deg(\tau, x_1) < \deg(u, x_1)$. See Theorem 2.6 of Geddes et al. (1992).

Step 6 in Algorithm 1 below shows where the MDP problem appears in multivariate Hensel lifting.

Algorithm 1 j th step of multivariate Hensel lifting for $j > 1$: Monic case.

Output: $\alpha_j \in \mathbb{Z}_p, a_j \in \mathbb{Z}_p[x_1, \dots, x_j], f_{j-1}, g_{j-1} \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$ where a_j, f_{j-1}, g_{j-1} are monic in x_1 and $a_j(x_j = \alpha_j) = f_{j-1}g_{j-1}$.

Input: $f_j, g_j \in \mathbb{Z}_p[x_1, \dots, x_j]$ such that $a_j = f_j g_j$ or FAIL.

- 1: $f_j \leftarrow f_{j-1}; g_j \leftarrow g_{j-1}$
 - 2: $\text{error} \leftarrow a_j - f_{j-1}g_{j-1}$
 - 3: **for** i from 1 while $\text{error} \neq 0$ and $\deg(f_j, x_j) + \deg(g_j, x_j) < \deg(a, x_j)$ **do**
 - 4: $c_i \leftarrow \text{coeff}(\text{error}, (x_j - \alpha_j)^i)$
 - 5: **if** $c_i \neq 0$ **then**
 - 6: Solve the MDP $\sigma_i g_{j-1} + \tau_i f_{j-1} = c_i$ in $\mathbb{Z}_p[x_1, \dots, x_{j-1}]$ for σ_i and τ_i .
 - 7: $(f_j, g_j) \leftarrow (f_j + \sigma_i \times (x_j - \alpha_j)^i, g_j + \tau_i \times (x_j - \alpha_j)^i)$
 - 8: $\text{error} \leftarrow a_j - f_j g_j$
 - 9: **end if**
 - 10: **end for**
 - 11: **if** $\text{error} = 0$ **then** return f_j, g_j **else** return FAIL **end if**
-

In Algorithm 1, the input conditions mean $\deg(\text{error}, x_1) < \deg(a_j, x_1)$ after Step 2 hence $\deg(c_1, x_1) < \deg(a_j, x_1)$. Hence the MDP $\sigma_1 g_{j-1} + \tau_1 f_{j-1} = c_1$ in Step 6 has a solution for σ_1 and τ_1 satisfying $\deg(\sigma_1, x_1) < \deg(f_{j-1}, x_1)$ and $\deg(\tau_1, x_1) < \deg(g_{j-1}, x_1)$. Thus the leading terms of f_j and g_j in x_1 are not changed in Step 7 so that after Step 8 we again have $\deg(\text{error}, x_1) < \deg(a_j, x_1)$. It follows that $\deg(c_i, x_1) < \deg(a_j, x_1)$ for all $i \geq 1$.

2.1. Wang’s MDP algorithm

To solve the MDP in Algorithm 1, for $j > 1$, Wang uses the same approach as for Hensel Lifting, that is, an ideal-adic approach which we present as Algorithm 2. For $j = 1$ the MDP is in $\mathbb{Z}_p[x_1]$ and is solved with the extended Euclidean algorithm. The division in Step 3 imposes condition (ii).

Algorithm 2 WMDS (Wang’s multivariate diophantine solver).

Input: Polynomials $u, w, c \in \mathbb{Z}_p[x_1, \dots, x_j]$ and an ideal $I = \langle x_2 - \alpha_2, \dots, x_n - \alpha_n \rangle$ with $n \geq j$ where $\gcd(u \bmod I, w \bmod I) = 1$ in $\mathbb{Z}_p[x_1]$ and degree bounds d_2, \dots, d_n satisfying $d_i \geq \max(\deg(\sigma, x_i), \deg(\tau, x_i))$ for $2 \leq i \leq n$. (One may use $d_i = \deg(a, x_i)$)

Output: $(\sigma, \tau) \in \mathbb{Z}_p[x_1, \dots, x_j]$ satisfying (i) $\sigma u + \tau w = c$, (ii) $\deg(\sigma, x_1) < \deg(w, x_1)$ and (iii) $\deg(\tau, x_1) < \deg(u, x_1)$ if $\deg(c, x_1) < \deg(u, x_1) + \deg(w, x_1)$, or, FAIL if no such solution exists.

```

1: if j = 1 then
2:   Solve  $su + tw = 1$  for  $s, t \in \mathbb{Z}_p[x_1]$  using the extended Euclidean algorithm.
3:   Let  $\sigma$  be the remainder of  $cs \div w$  and  $\tau$  be the quotient of  $(c - \sigma u) \div w$ .
4:   return  $(\sigma, \tau)$ 
5: end if
6:  $(\sigma_0, \tau_0) \leftarrow \text{WMDS}(u(x_j = \alpha_j), w(x_j = \alpha_j), c(x_j = \alpha_j), I)$ 
7: if WMDS returned FAIL then return FAIL end if
8:  $(\sigma, \tau) \leftarrow (\sigma_0, \tau_0)$ 
9: error  $\leftarrow c - \sigma u - \tau w$ 
10: for  $i = 1, 2, \dots, d_j$  while error  $\neq 0$  do
11:    $c_i \leftarrow \text{coeff}(\text{error}, (x_j - \alpha_j)^i)$ 
12:   if  $c_i \neq 0$  then
13:      $(s, t) \leftarrow \text{WMDS}(\sigma_0, \tau_0, c_i, I)$ 
14:     if WMDS return FAIL then return FAIL end if
15:      $(\sigma, \tau) \leftarrow (\sigma + s(x_j - \alpha_j)^i, \tau + t(x_j - \alpha_j)^i)$ 
16:     error  $\leftarrow c - \sigma u - \tau w$ 
17:   end if
18: end for
19: if error = 0 then return  $(\sigma, \tau)$  else return FAIL end if

```

In general, if $\alpha_j \neq 0$ then the Taylor expansion of σ and τ about $x_j = \alpha_j$ in Algorithm 2 is dense in x_j so the $c_i \neq 0$. If we let $d_j = \deg(a_j, x_j)$ and $M(x_j)$ be the number of calls to the Euclidean algorithm in Step 2 of Algorithm 2, then $M(x_1) = 1$ and $M(x_j) \leq (d_j - 1)M(x_{j-1})$ thus $M(x_{n-1}) \leq \prod_{i=2}^{n-1} (d_i - 1)$. If all $\alpha_j \neq 0$ for $2 \leq j \leq n - 1$ then $M(x_{n-1})$ becomes exponential in n . It is this exponential behavior that sparse multivariate diophantine solvers eliminate. On the other hand, if MHL can choose some α_j to be 0, for example, if the input polynomial $a(x_1, \dots, x_n)$ is monic in x_1 , or perhaps monic in another variable, then this exponential behavior may not occur for sparse f and g .

2.2. Solution to the MDP via interpolation

We consider whether we can interpolate x_2, \dots, x_j in σ and τ in (1) using sparse interpolation methods. If $\beta \in \mathbb{Z}_p$ with $\beta \neq \alpha_j$, then

$$\sigma(x_j = \beta) u(x_j = \beta) + \tau(x_j = \beta) w(x_j = \beta) = c(x_j = \beta) \bmod I_{j-1}^{d_{j-1}+1}.$$

For $K_j = \langle x_2 - \alpha_2, \dots, x_{j-1} - \alpha_{j-1}, x_j - \beta \rangle$ and $G_j = \text{GCD}(u \bmod K_j, w \bmod K_j)$, we obtain the unique solution $\sigma(x_j = \beta)$ iff $G_j = 1$. However $G_j \neq 1$ is possible. Let $R = \text{res}(u, w, x_1)$ be the Sylvester resultant of u and w taken in x_1 . Since u, w are monic in x_1 one has²

$$G_j \neq 1 \iff \text{res}(u \bmod K_j, w \bmod K_j, x_1) = 0 \iff R(\alpha_2, \dots, \alpha_{j-1}, \beta) = 0.$$

Let $r = R(\alpha_2, \dots, \alpha_{j-1}, x_j) \in \mathbb{Z}_p[x_j]$ so that $R(\alpha_2, \dots, \alpha_{j-1}, \beta) = r(\beta)$. We recall Bezout's theorem which says $\deg(R) \leq \deg(u)\deg(w)$. Now if β is chosen at random from \mathbb{Z}_p and $\beta \neq \alpha_j$ then

$$\Pr[G_j \neq 1] = \Pr[r(\beta) = 0] \leq \frac{\deg(r, x_j)}{p-1} \leq \frac{\deg(u)\deg(w)}{p-1}.$$

This bound for $\Pr(G_j \neq 1)$ is a worst case bound. In Monagan and Tuncer (2016a) we show that the average probability for $\Pr[G_j \neq 1] = 1/(p-1)$. Thus if p is large, the probability that $G_j = 1$ is high. Interpolation is thus an option to solve the MDP. If $G_j \neq 1$, we could choose another β but our implementation simply returns FAIL and we restart the factorization of a by choosing a new evaluation point $\alpha = (\alpha_2, \dots, \alpha_n) \in \mathbb{Z}^{(n-1)}$.

2.3. Solution to the MDP via sparse interpolation

Following the sparse interpolation idea of Zippel (1990), given a sub-solution $\sigma_j(x_j = \alpha_j)$ we use the support of $\sigma_j(x_j = \alpha_j)$ to obtain $\sigma_j(x_j = \beta_k)$ for other $\beta_k \in \mathbb{Z}_p$. Then one interpolates x_j . We could interpolate x_2, \dots, x_{j-1} in $\sigma_j(x_j = \beta_k)$ from univariate images in $\mathbb{Z}_p[x_1]$. To reduce the work we interpolate x_3, \dots, x_{j-1} in $\sigma_j(x_j = \beta_k)$ from bivariate images in $\mathbb{Z}_p[x_1, x_2]$ because this will likely reduce s (see Algorithm 4 Step 2) the number of images needed to interpolate $\sigma_j(x_j = \beta_k)$ which reduces the evaluation cost and the size of the linear systems to be solved.

We wish to estimate the gain we will make by using bivariate images instead of univariate images. A dense polynomial $h(x_1, \dots, x_m)$ in m variables of total degree d has $\binom{d+m}{m}$ terms. The coefficient in x_1 with the most terms is the coefficient in x_1^0 . It has $\binom{d+m-1}{m-1}$ terms. Thus we need $\binom{d+m-1}{m-1}$ univariate images to interpolate h . If we interpolate h from bivariate images the coefficient in x_1 and x_2 with the most terms is the coefficient in $x_1^0 x_2^0$. It has $\binom{d+m-2}{m-2}$ terms. Hence we reduce the number of images by a factor of $\binom{d+m-1}{m-1} / \binom{d+m-2}{m-2} = \frac{d+m-1}{m-1}$. For sparse h with many terms, the gain will be close to $\frac{d+m-1}{m-1}$.

Suppose the form of σ_j is

$$\sigma_f = \sum_{i+k \leq d} c_{ik}(x_3, \dots, x_j) x_1^i x_2^k \text{ where } c_{ik} = \sum_{l=0}^{s_{ik}} c_{ikl} x_3^{l_3} \dots x_j^{l_j} \text{ with } c_{ikl} \in \mathbb{Z}_p \setminus \{0\}$$

and the total degree of σ_j in x_1, x_2 is bounded by d . Let $s = \max s_{ik}$ be the maximum number of terms in the coefficients of σ_f . We obtain each c_{ik} by solving $\mathcal{O}(d^2)$ linear systems of size at most $s \times s$. As explained in Zippel (1990), each linear system can be solved in $\mathcal{O}(s_{ik}^2)$ arithmetic operations in \mathbb{Z}_p and using $\mathcal{O}(s_{ik})$ space. We then interpolate x_j in σ_j from $\sigma_j(x_j = \beta_k)$ for $k = 0, \dots, \deg(\sigma_j, x_j)$. Finally we compute $\tau_j = (c_j - \sigma_j u_j) / w_j$. If this division fails it means that σ_f is wrong; we restart the factorization of $a(x_1, \dots, x_n)$ with a new evaluation point α .

To solve an MDP in $\mathbb{Z}_p[x_1, x_2]$ we use a modular algorithm that interpolates x_2 from univariate images in $\mathbb{Z}_p[x_1]$. Because polynomials in many variables with many terms are likely to have dense bivariate images, we use dense univariate interpolation. The algorithm, which is probabilistic, and its complexity analysis are given in Appendix B. It does $\mathcal{O}(d^3)$ arithmetic operations in \mathbb{Z}_p where d bounds the total degree of the input polynomials in x_1 and x_2 . Because our bivariate Diophantine solver (BDP) is called many times in Algorithm 4, and because it does a lot of arithmetic in \mathbb{Z}_p , we implemented it in the C programming language for efficiency.

² This argument also works for the non-monic case if the leading coefficients of u and w w.r.t. x_1 do not vanish at $(\alpha_2, \dots, \alpha_n)$ modulo p , conditions which are imposed by Wang's MHL.

This multivariate MDP solving algorithm is presented as Algorithm MDSolver. Following this we present the sparse interpolation algorithm used in Step 11.

Algorithm 3 MDSolver.

Input: Polynomials $u, w, c \in \mathbb{Z}_p[x_1, x_2, \dots, x_j]$ where $j \geq 2$, p is a large prime and the MDP conditions (see Section 2) are satisfied.

Output: $(\sigma, \tau) \in \mathbb{Z}_p[x_1, x_2, \dots, x_j]$ such that $\sigma u + \tau w = c \in \mathbb{Z}_p[x_1, x_2, \dots, x_j]$.

- 1: **if** $j = 2$ **then** call BDP to return $(\sigma, \tau) \in \mathbb{Z}_p[x_1, x_2]$ or FAIL **end if**.
- 2: Pick $\beta_1 \in \mathbb{Z}_p$ at random
- 3: $(u_{\beta_1}, w_{\beta_1}, c_{\beta_1}) \leftarrow (u(x_j=\beta_1), w(x_j=\beta_1), c(x_j=\beta_1))$.
- 4: $(\sigma_1, \tau_1) \leftarrow \text{MDSolver}(u_{\beta_1}, w_{\beta_1}, c_{\beta_1})$. // this MDP has one less variable
- 5: **if** $\sigma_1 = \text{FAIL}$ **then** return FAIL **end if**
- 6: $k \leftarrow 1$; $\sigma \leftarrow \sigma_1$; $q \leftarrow (x_j - \beta_1)$; $\sigma_f \leftarrow \sigma_1$.
- 7: **repeat**
- 8: $h \leftarrow \sigma$
- 9: Set $k \leftarrow k + 1$ and pick $\beta_k \in \mathbb{Z}_p$ at random distinct from $\beta_1, \dots, \beta_{k-1}$
- 10: $(u_{\beta_k}, w_{\beta_k}, c_{\beta_k}) \leftarrow (u(x_j=\beta_k), w(x_j=\beta_k), c(x_j=\beta_k))$.
- 11: $(\sigma_k, \tau_k) \leftarrow \text{SparseInterpolate}(u_{\beta_k}, w_{\beta_k}, c_{\beta_k}, \sigma_f)$ // Algorithm 4
- 12: **if** $\sigma_k = \text{FAIL}$ **then** return FAIL **end if**
- 13: Solve $\{\sigma = h \bmod q \text{ and } \sigma = \sigma_k \bmod (x_j - \beta_k)\}$ for $\sigma \in \mathbb{Z}_p[x_1, x_2, \dots, x_j]$.
- 14: $q \leftarrow q \cdot (x_j - \beta_k)$
- 15: **until** $\sigma = h$ and $w|(c - \sigma u)$
- 16: Set $\tau \leftarrow (c - \sigma u)/w$ and return (σ, τ) .

Algorithm SparseInterpolate interpolates σ only and obtains τ by division in Step 19. The division also detects an incorrect σ_f . As an alternative design one could interpolate both σ and τ and then test if $c - \sigma u - \tau w = 0$. The reason we interpolate σ only is it's faster if $\#\sigma$ is smaller than $\#\tau$, more precisely if s the number of bivariate images needed to interpolate σ is significantly fewer than the number needed to interpolate τ .

The linear systems in Step 15 are Vandermonde systems. Because the monomial evaluations m_{ikl} are required to be unique in Step 5, these Vandermonde systems have a unique solution.

2.4. The evaluation cost of algorithm SparseInterpolate

Suppose $f = \sum_{i=1}^t c_i X_i Y_i$ where X_i is a monomial in x_1, x_2 and Y_i is a monomial in x_3, \dots, x_n and $0 \neq c_i \in \mathbb{Z}_p$. In sparse interpolation we pick non-zero β_3, \dots, β_n from \mathbb{Z}_p at random and at Step 7 compute s evaluations

$$f_j := f(x_1, x_2, x_3=\beta_3^j, \dots, x_n=\beta_n^j), \text{ for } j = 1, \dots, s.$$

We can take advantage of the form of the evaluation points. First we sort the t monomials in f on x_1 and x_2 so that all monomials in $x_1^i x_2^j$ appear together. As an example consider

$$f = x_1^5 + 72x_1^3 x_2^4 x_4 x_5 + 37x_1 x_2^5 x_3^2 x_4 - 92x_1 x_2^5 x_5^2 + 6x_1 x_2^3 x_3 x_4^2.$$

Here $x_1^5 > x_1^3 x_2^4 > x_1 x_2^5 = x_1 x_2^5 > x_1 x_2^5$ in lexicographical order. Our goal is to compute

$$f_j = x_1^5 + 72(\beta_4 \beta_5)^j x_1^3 x_2^4 + 37(\beta_3^2 \beta_4)^j x_1 x_2^5 - 92(\beta_5^2)^j x_1 x_2^5 + 6(\beta_3 \beta_4^2)^j x_1 x_2^3,$$

for $1 \leq j \leq s$. First we initialize two arrays of size t

$$c^{(0)} := [1, 72, 37, -92, 6] \quad \text{and} \quad \theta := [1, \beta_4 \beta_5, \beta_3^2 \beta_4, \beta_5^2, \beta_3 \beta_4^2].$$

Algorithm 4 SparseInterpolate: solve an MDP using a sparse interpolation.

Input: Polynomials $u, w, c, \sigma_f \in \mathbb{Z}_p[x_1, x_2, \dots, x_{j-1}]$ where u, w are monic in x_1 .

Output: The solution (σ, τ) to the MDP $\sigma u + \tau w = c \in \mathbb{Z}_p[x_1, x_2, \dots, x_{j-1}]$ or FAIL.

- 1: Let $\sigma = \sum_{i,k} c_{ik}(x_3, \dots, x_{j-1}) x_1^i x_2^k$ where $c_{ik} = \sum_{l=1}^{s_{ik}} c_{ikl} M_{ikl}$ with c_{ikl} unknown coefficients to be solved for and $x_1^i x_2^k M_{ikl}$ are the monomials in $\text{Supp}(\sigma_f)$.
- 2: Let $s = \max s_{ik} = \max \#c_{ik}$.
- 3: Pick $(\beta_3, \dots, \beta_{j-1}) \in (\mathbb{Z}_p \setminus \{0\})^{j-3}$ at random.
- 4: Compute monomial evaluation sets

$$S_{ik} \leftarrow \{m_{ikl} = M_{ikl}(\beta_3, \dots, \beta_{j-1}) : 1 \leq l \leq s_{ik}\} \text{ for each } i, k$$

- 5: **if** $|S_{ik}| \neq s_{ik}$ for some ik **then** return FAIL **end if** // p is likely too small
- 6: **for** i from 1 to s **do** // Compute the bivariate images of σ
- 7: Let $Y_i = (x_3 = \beta_3^i, \dots, x_{j-1} = \beta_{j-1}^i)$.
- 8: Evaluate $u(x_1, x_2, Y_i), w(x_1, x_2, Y_i), c(x_1, x_2, Y_i)$ by the method in section 2.3.
- 9: Solve $\sigma_i(x_1, x_2)u(x_1, x_2, Y_i) + \tau_i(x_1, x_2)w(x_1, x_2, Y_i) = c(x_1, x_2, Y_i)$ in $\mathbb{Z}_p[x_1, x_2]$ for $\sigma_i(x_1, x_2)$ using Algorithm BDP (see Appendix B)
- 10: **if** BDP returns FAIL **then**
- 11: return FAIL // BDP chose $\gamma \in \mathbb{Z}_p$ and $\gcd(u(x_1, \gamma, Y_i), w(x_1, \gamma, Y_i)) \neq 1$.
- 12: **end if**
- 13: **end for**
- 14: **for** each i, k **do**
- 15: Construct and solve the following $s_{ik} \times s_{ik}$ linear system for the coefficients c_{ikl} .

$$\left\{ \sum_{l=1}^{s_{ik}} c_{ikl} m_{ikl}^n = \text{coefficient of } x_1^i x_2^k \text{ in } \sigma_n(x_1, x_2) \text{ for } 1 \leq n \leq s_{ik} \right\}$$

- 16: **end for**
- 17: Substitute the solutions for c_{ikl} into σ
- 18: **if** $w \mid (c - \sigma u)$ **then**
- 19: Set $\tau = (c - \sigma u)/w$ and **return** (σ, τ)
- 20: **else**
- 21: return FAIL // σ_f is wrong
- 22: **end if**

Then in a loop for $i = 1, 2, \dots, s$ we update the coefficient array $c^{(j-1)}$ by the monomial array θ by computing $c_i^{(j)} = c_i^{(j-1)} \times \theta_i$ for $1 \leq i \leq t$ so that each iteration computes the coefficient array

$$c^{(j)} = [1, 72(\beta_4\beta_5)^j, 37(\beta_3^2\beta_4)^j, -92(\beta_5^2)^j, 6(\beta_3\beta_4^2)^j],$$

using t multiplications in \mathbb{Z}_p . Then adding the coefficients of like terms we get

$$f_j = x_1^5 + 72(\beta_4^j\beta_5^j)x_1^3x_2^4 + (37(\beta_3^j)^2\beta_4^j - 92(\beta_5^j)^2)x_1x_2^5 + 6\beta_3^j(\beta_4^j)^2x_1x_2^3.$$

To compute θ we construct $n - 2$ tables B_j for $j \leq n$ of powers where $B_{ji} = \beta_j^i$ for $0 \leq i \leq d$. Next we evaluate Y_i at $(\beta_3, \dots, \beta_n)$ in $(n - 3)$ multiplications using tables of powers of β_3, \dots, β_n . The cost of computing $n - 2$ tables of powers is $\leq (n - 2)d$ multiplications in \mathbb{Z}_p . The cost of computing the array θ is $\leq t(n - 3)$ multiplications. After constructing θ the cost of each of the s evaluations is t multiplications and $\leq t$ additions in \mathbb{Z}_p . Hence the total cost is bounded above by $C_N = st + t(n - 3) + (n - 2)d$ multiplications in \mathbb{Z}_p .

We note that because evaluation is one of the bottlenecks of our sparse factorization algorithm, Roman Pearce implemented this evaluation algorithm for us in the C programming language for efficiency.

3. Sparse Hensel lifting

3.1. The main idea of SHL

Factoring multivariate polynomials via Sparse Hensel Lifting (SHL) uses the same idea of sparse interpolation. Following the same notation introduced in Section 1, at $(j - 1)$ th step of MHL we have

$$f_{j-1} = x_1^{df} + c_{j1}M_1 + \dots + c_{jt_j}M_{t_j}$$

where $df = \deg(f_{j-1}, x_1)$, $t_j + 1$ is the number of non-zero terms that appear in f_{j-1} , the M_k 's are distinct monomials in x_1, \dots, x_{j-1} and $c_{jk} \in \mathbb{Z}_p$ for $1 \leq k \leq t_j$. Then at the j th step SHL assumes

$$f_j = x_1^{df} + \Lambda_{j1}M_1 + \dots + \Lambda_{jt_j}M_{t_j}$$

where for $1 \leq k \leq t_j$,

$$\Lambda_{jk} = \sum_{i=0}^{d_{jk}} c_{ijk}(x_j - \alpha_j)^i$$

for some degrees $d_{jk} = \deg(\Lambda_{jk}, x_j)$ and coefficients $c_{ijk} \in \mathbb{Z}_p$ with $c_{0jk} = c_{jk}$. We will call this assumption the **weak SHL assumption**. This assumption is the same for the factor g_{j-1} . For example, consider $f_j = f_3 = x_1^3 - x_1x_2x_3 + x_1x_2x_3^3 - 3x_2^2$. If $\alpha_3 = 1$ so that $f_{j-1} = f_2 = x_1^3 - 3x_2^2$, the weak SHL assumption is false because the monomial x_1x_2 does not appear in f_2 . On the other hand if $\alpha_3=2$ we have $f_{j-1} = f_2 = x_1^3 + 6x_1x_2 - 3x_2^2$ and the weak SHL assumption is true.

To recover f_j from f_{j-1} and g_j from g_{j-1} , during the j th step of MHL (see Algorithm 1) one starts with $\sigma_0 := f_{j-1}$, $\tau_0 := g_{j-1}$, then in a for loop starting from $i = 1$, for non-zero Taylor coefficients c_i , one solves the MDPs $\sigma_i g_{j-1} + \tau_i f_{j-1} = c_i$ for $1 \leq i \leq d_j$ for some d_j . After the loop terminates we have $f_j = \sum_{k=0}^{d_j} \sigma_k(x_j - \alpha_j)^k$. On the other hand if the weak SHL assumption is true then we also have

$$f_j = x_1^{df} + \sum_{k=1}^{t_j} \underbrace{\left(\sum_{i=0}^{d_{jk}} c_{ijk}(x_j - \alpha_j)^i \right)}_{\Lambda_{jk}} M_k = x_1^{df} + \sum_{i=0}^{d_{jk}} \underbrace{\left(\sum_{k=1}^{t_j} c_{ijk}M_k \right)}_{\sigma_k} (x_j - \alpha_j)^i.$$

Similarly for g_j . Hence if the weak SHL assumption is true then the support of each σ_k will be a subset of support of f_{j-1} . Therefore we can use f_{j-1} as a skeleton of the solution of each σ_k . The same is true for τ_k . Although it is not stated explicitly in Kaltofen (1985), this is one of the underlying ideas of Kaltofen's SHL.

3.2. Our SHL organization

Before presenting our SHL organization (Algorithm 5 MTSHL), we make the following key observation which has been proven in Monagan and Tuncer (2016b).

Lemma 1. Let $f \in \mathbb{Z}_p[x_1, \dots, x_n]$ and let α be a randomly chosen element in \mathbb{Z}_p and $f = \sum_{i=0}^{d_n} b_i(x_1, \dots, x_{n-1})(x_n - \alpha)^i$ where $d_n = \deg(f, x_n)$. Then

$$\Pr[\text{Supp}(b_{j+1}) \not\subseteq \text{Supp}(b_j)] \leq |\text{Supp}(b_{j+1})| \frac{d_n - j}{p - d_n + j + 1} \text{ for } 0 \leq j < d_n.$$

Lemma 1 shows that for the sparse case, if p is big enough then the probability of $\text{Supp}(b_{j+1}) \subseteq \text{Supp}(b_j)$ is high. This observation suggests we use σ_{i-1} as a form of the solution of σ_i . We call this assumption $\text{Supp}(\sigma_i) \subseteq \text{Supp}(\sigma_{i-1})$ for all $i > 0$ the **strong SHL assumption**. Based on this observation

Algorithm 5 j th step of MTSHL for $j > 1$.

Input: $\alpha_j \in \mathbb{Z}_p$ and $a_j \in \mathbb{Z}_p[x_1, \dots, x_j]$, $f_{j-1}, g_{j-1} \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$ where a_j, f_{j-1}, g_{j-1} are monic in x_j and satisfy $a_j(x_j = \alpha_j) = f_{j-1}g_{j-1}$.

Output: $f_j, g_j \in \mathbb{Z}_p[x_1, \dots, x_j]$ such that $a_j = f_jg_j$ or FAIL.

- 1: **if** $\#f_{j-1} > \#g_{j-1}$ **then** interchange f_{j-1} with g_{j-1} **end if**
- 2: $(\sigma_0, \tau_0) \leftarrow (f_{j-1}, g_{j-1})$.
- 3: $(f_j, g_j) \leftarrow (f_{j-1}, g_{j-1})$.
- 4: $\text{error} \leftarrow a_j - f_jg_j$; $\text{monomial} \leftarrow 1$.
- 5: **for** $i = 1, 2, 3, \dots$ **while** $\text{error} \neq 0$ and $\deg(f_j, x_i) + \deg(g_j, x_i) < \deg(a_j, x_i)$ **do**
- 6: $\text{monomial} \leftarrow \text{monomial} \times (x_i - \alpha_j)$.
- 7: $c_i \leftarrow \text{coeff}(\text{error}, (x_j - \alpha_j)^i)$.
- 8: **if** $c_i \neq 0$ **then**
- 9: // Solve the MDP $\sigma_i g_{j-1} + \tau_i f_{j-1} = c_i$ for σ_i and τ_i in $\mathbb{Z}_p[x_1, \dots, x_{j-1}]$
- 10: $\sigma_i \leftarrow \sigma_{i-1}$. // **strong SHL assumption:** assume $\text{Supp}(\sigma_i) \subseteq \text{Supp}(\sigma_{i-1})$
- 11: $(\sigma_i, \tau_i) \leftarrow \text{SparseInterpolate}(g_{j-1}, f_{j-1}, c_i, \sigma_i)$ // Algorithm 4
- 12: **if** $(\sigma_i, \tau_i) = \text{FAIL}$ **then** $(\sigma_i, \tau_i) \leftarrow \text{MDSolver}(f_{j-1}, g_{j-1}, c_i)$ **end if**
- 13: **if** $(\sigma_i, \tau_i) = \text{FAIL}$ **then** restart MTSHL with a new evaluation point α **end if**
- 14: $(f_j, g_j) \leftarrow (f_j + \sigma_i \times \text{monomial}, g_j + \tau_i \times \text{monomial})$.
- 15: $\text{error} \leftarrow a_j - f_jg_j$.
- 16: **end if**
- 17: **end for**
- 18: **if** $\text{error} = 0$ **then** return(f_j, g_j) **else** return FAIL **end if**

the j th step of our SHL organization is summarized in Algorithm 5. See Appendix A for a concrete example.

Algorithm 5 (MTSHL) calls Algorithm 4 (SparseInterpolate) at Step 11 with inputs $u = g_{j-1}$, $w = f_{j-1}$, and $c = c_i$ in $\mathbb{Z}_p[x_1, \dots, x_{j-1}]$. Algorithm 4 is probabilistic. If we assume $\text{Supp}(\sigma_f) \supseteq \sigma_i$ then Algorithm 4 can fail in Step 5 or in Step 10. To bound the probability of this failure we make use of the Schwartz-Zippel lemma below.

Lemma 2. (Schwartz, 1980; Zippel, 1979) *Let F be a field and $f \neq 0$ be a polynomial in $F[x_1, x_2, \dots, x_n]$ with total degree D and let $S \subseteq F$. Then the number of roots of f in S^n is at most $D|S|^{n-1}$. Hence if β is chosen at random from S^n then $\text{Prob}[f(\beta) = 0] \leq \frac{D}{|S|}$.*

Since $d = \deg a$ and $a = fg$ we have $\deg f < d$ and $\deg g < d$ hence $\deg f_{j-1} < d$ thus $\deg \sigma_i < d$ and $\deg \tau_i < d$. Now at Step 5, Algorithm 4 evaluates the monomials M_{ikl} that appear in $\text{Supp}(\sigma_f)$ at non-zero random points $\beta_3, \dots, \beta_{j-1}$ from \mathbb{Z}_p . Consider the polynomials

$$\Delta_{ik} = \prod_{1 \leq a < b \leq s_{ik}} (M_{ika} - M_{ikb}) \in \mathbb{Z}_p[x_3, \dots, x_{j-1}].$$

In Step 5, $|S_{ik}| = s_{ik}$ means the monomial evaluations are distinct, and if this is not the case, then at least one of the Vandermonde matrices constructed in Step 15 is not invertible. In that case, $\Delta_{ik}(\beta_3, \dots, \beta_{j-1}) = 0$. We want to bound the probability that this may happen for any Δ_{ik} . Let $\Delta = \prod \Delta_{ik}$. Then $\Delta(\beta_3, \dots, \beta_{j-1}) = 0$ means one or more monomial sets are not distinct. Since $\beta_3, \dots, \beta_{j-1}$ were chosen at random from $[1, p - 1]$, we have by Schwartz-Zippel

$$\text{Pr}[\Delta(\beta_3, \dots, \beta_{j-1}) = 0] \leq \frac{\deg(\Delta)}{p - 1}.$$

We have $\deg M_{ikl} < d$ and $\deg \Delta < \sum_{0 \leq i+k \leq d} d \binom{s_{ik}}{2}$. Note that $\sum s_{ik} = T_{f_{j-1}}$ and $\deg \Delta$ is maximized when one of the coefficients has all $T_{f_{j-1}}$ terms, that is, some $s_{ik} = T_{f_{j-1}} \leq T_f$. Thus, $\deg \Delta \leq d \binom{T_f}{2}$ and we obtain

$$\text{Pr}[\Delta(\beta_3, \dots, \beta_{j-1}) = 0] \leq \frac{dT_f^2}{2(p - 1)}.$$

So for $p > dT_f^2$, we expect that $(\beta_3, \dots, \beta_{j-1})$ will satisfy the condition $|S_{ik}| = s_{ik}$ in Step 5. We remark that the T_f^2 factor in the bound cannot be reduced to T_f^1 since fundamentally, this is a birthday problem as the monomial evaluations m_{ikl} must be distinct in \mathbb{Z}_p . In our experiments in Section 8 we used $p = 2^{31} - 1$ which is not very large. Even though T_f is quite large for some of the experiments, $s = \max s_{ik}$ is significantly less than T_f , Algorithm 4 never failed at Step 5 in our experiments. For example, in Table 6 for $n = 14$, we have $T_f = T_g = 34,937$ but $s = s_{00} = 9,705$ for this example. For a more robust implementation of Algorithm MTSHL we would recommend using a 63 bit prime on a 64 bit machine so that $p \gg ds^2$.

Algorithm 4 chooses $\beta_3, \dots, \beta_{j-1}$ at random in Step 3. In Step 8 it evaluates u, w and c at powers $Y_i = (\beta_3^i, \dots, \beta_{j-1}^i)$ for $1 \leq i \leq s$ where s is defined in Step 2. Then, for each i , it calls Algorithm BDP in Step 9 with input $u(x_1, x_2, Y_i), w(x_1, x_2, Y_i)$ and $c(x_1, x_2, Y_i)$.

Since $\deg \sigma_i(x_1, x_2) \leq \deg \sigma < d$, Algorithm BDP needs at most d points to interpolate x_2 in $\sigma_i(x_1, x_2)$. Algorithm BDP uses random points γ_{ik} from \mathbb{Z}_p to do this. It first solves

$$\sigma_{ik} g_{j-1}(x_1, \gamma_{ik}, Y_i) + \tau_{ik} f_{j-1}(x_1, \gamma_{ik}, Y_i) = c(x_1, \gamma_{ik}, Y_i)$$

for $\sigma_{ik}, \tau_{ik} \in \mathbb{Z}_p[x_1]$. To solve these univariate diophantine equations BDP requires

$$g_{ik} := \gcd(g_{j-1}(x_1, \gamma_{ik}, Y_i), f_{j-1}(x_1, \gamma_{ik}, Y_i)) = 1.$$

If any $g_{ik} \neq 1$ then (γ_{ik}, Y_i) is unlucky and Algorithm BDP fails and hence Algorithm 4 fails. To bound the probability that Algorithm 4 fails in this way let $R = \text{res}(g_{j-1}, f_{j-1}, x_1) \in \mathbb{Z}_p[x_2, \dots, x_{j-1}]$. Now $\deg g_{j-1} < d$ and $\deg f_{j-1} < d$ imply $\deg R < d^2$. Since f and g (and hence f_{j-1} and g_{j-1}) are monic in x_1 we have

$$g_{ik} \neq 1 \iff R(\gamma_{ik}, Y_i) = 0.$$

Thus we need to bound the probability that $R(\gamma_{ik}, Y_i) = 0$ for any $1 \leq k \leq d, 1 \leq i \leq s$. To use the Schwartz-Zippel Lemma here we face two obstacles. First, the powers $Y_i = \beta_3^i, \dots, \beta_{j-1}^i$ are not random even though $\beta_3, \dots, \beta_{j-1}$ is random. Second, for each Y_i Algorithm BDP chooses several random γ_{ik} . Let

$$S = \prod_{i=1}^s R(x_2, x_3^i, \dots, x_{j-1}^i)$$

Since $\deg(R) < d^2$ we have

$$\deg S = \sum_{i=1}^s i \deg R < \sum_{i=1}^s id^2 = \frac{s(s+1)}{2} d^2 \leq s^2 d^2.$$

Now let

$$R_i = R(x_2, Y_i) \text{ for } 1 \leq i \leq s.$$

Algorithm BDP fails if either $R_i = R(x_2, Y_i) = 0$ for some i or $R_i \neq 0$ for some i and $R_i(\gamma_{ik}) = 0$ for some k . We now bound the probability of each case. Let β_2 be random in \mathbb{Z}_p . Then

$$\begin{aligned} \Pr[R(x_2, Y_i) = 0 \text{ for some } i] &= \Pr[S(x_1, \beta_3, \dots, \beta_{j-1}) = 0] \\ &\leq \Pr[S(\beta_2, \beta_3, \dots, \beta_{j-1}) = 0] \\ &\leq \frac{\deg S}{p-1} \text{ by Schwartz-Zippel} \\ &\leq \frac{d^2 s^2}{p-1}. \end{aligned}$$

Now since $R_i \in \mathbb{Z}_p[x_2]$ and $\deg R_i \leq \deg R < d^2$,

$$\Pr[R_i(\gamma_{ik}) = 0 \text{ for some } i, k \mid R_i \neq 0] \leq \frac{\deg R_i}{p} ds < \frac{d^3 s}{p}.$$

Adding the two failure probabilities and using $s \leq T_f$ we have

$$\Pr[R(\gamma_{ik}, \beta_3^i, \dots, \beta_{j-1}^i) = 0 \text{ for some } i, k] \leq \frac{d^2 s^2}{p-1} + \frac{d^3 s}{p} < \frac{d^2 T_f (d + T_f)}{p-1}$$

Finally, adding the two possibilities of failure at Steps 5 and 10 we have the following.

Proposition 3. Let $d = \deg a$ and $T_f = \#f$. When Algorithm 5 calls Algorithm 4 with input $u = g_{j-1}$, $w = f_{j-1}$, $c = c_i$, and $\sigma_f = f_{j-1}$, if $\text{Supp}(\sigma_f) \supseteq \text{Supp}(f_j)$ then Algorithm 4 fails to compute (σ_i, τ_i) in Step 11 of Algorithm 5 with probability less than

$$\underbrace{\frac{dT_f^2}{2(p-1)}}_{\text{Step 5}} + \underbrace{\frac{d^2 T_f (d + T_f)}{p-1}}_{\text{Step 10}} = \frac{dT_f ((d + \frac{1}{2})T_f + d^2)}{p-1}.$$

4. The expected number of terms after evaluation

The complexity of MTSHL depends on the number of terms in the factors, and the number of terms of each factor is expected to decrease from the step $j + 1$ to j after evaluation. To make our complexity analysis as precise as possible, we need to give an upper bound for the expected sizes of the factors in each step j . In this section we will compute these bounds and confirm our theoretical bounds with experimental data.

Let p be a big prime and $f \in \mathbb{Z}_p[x_1, \dots, x_n]$ be a randomly chosen multivariate polynomial of degree $\leq d$ that has T non-zero terms. Let $s = \binom{n+d}{n}$ be the number of all possible monomials of degree $\leq d$. An upper bound for T is then given by $T \leq s$. By randomly chosen we mean that the probability of occurrence of each monomial is the same and equal to $1/s$. So we think of choosing a random polynomial of degree $\leq d$ that has T terms as choosing T distinct monomials out of s choices and choosing coefficients uniformly at random from $[1, p - 1]$.

Let also $g = f(x_n = \alpha_n)$ for a randomly chosen non-zero element $\alpha_n \in \mathbb{Z}_p$. Before evaluation let $f = \sum_{i=1}^t \mathbf{m}_i c_i(x_n)$ where \mathbf{m}_i are monomials in the variables x_1, \dots, x_{n-1} . Then $T = \sum_{i=1}^t \#c_i(x_n)$ and $g = \sum_{i=1}^t \mathbf{m}_i c_i(\alpha_n)$. One has

$$\Pr[c_i(\alpha_n) = 0] \leq \frac{\deg(c_i, x_n)}{p-1} \leq \frac{d}{p-1}$$

for each i . If p is much bigger than d and α_n is random, we expect $c_i(\alpha_n) \neq 0$ for $1 \leq i \leq t$. In the following first we will assume that $c_i(\alpha_n) \neq 0$ for $1 \leq i \leq t$ and compute the expected value of number of terms T_g of g , in terms of T, d and n . Then the upper bounds on the expected value of T_g will be valid even for the case in which some of the $c_i(\alpha_n) = 0$.

Let Y_k be a random variable that counts the number of terms of the k th homogeneous component f_k of f which is homogeneous of degree k in the variables x_1, \dots, x_{n-1} . Then $f = \sum_{k=0}^d f_k$ and $\deg(f_k, x_n) \leq d - k$ for $0 \leq k \leq d$.

Example 4. Let $n = 3, d = 6$ and let

$$f = \underbrace{1 + x_3^5}_{f_0} + \underbrace{2x_1x_3^4}_{f_1} + \underbrace{x_1x_2^2(3x_3 + 4x_3^2)}_{f_3} + \underbrace{5x_1^2x_2x_3^3 + x_1^2x_2^2(6x_3 + 7x_3^2)}_{f_4} + \underbrace{8x_1^3x_2^3}_{f_6}$$

with $f_2 = f_5 = 0$. Then $Y_0 = 2, Y_1 = 1, Y_3 = 3, Y_4 = 2, Y_6 = 1$, and $Y_2 = Y_5 = 0$.

Let s_k be the number of all possible monomials in the variables x_1, \dots, x_{n-1} with homogeneous degree k , i.e. $s_k = \binom{n-2+k}{n-2}$ and let $d_k = d - k + 1$ for $0 \leq k \leq d$. Since the number of all possible monomials in x_1, \dots, x_n up to degree d which are homogeneous of degree k in the variables x_1, \dots, x_{n-1} is $s_k d_k$, we have $\sum_{k=0}^d s_k d_k = \binom{n+d}{n} = s$ and

$$\Pr[Y_k = j] = \frac{1}{\binom{s}{T}} \binom{s_k d_k}{j} \binom{s - s_k d_k}{T - j}.$$

This is a hypergeometric distribution with expected value and variance

$$E[Y_k] = T \frac{s_k d_k}{s} \text{ and } \text{Var}[Y_k] = \frac{(s - s_k d_k)(s - T)T s_k d_k}{s^2(s - 1)}.$$

See formula 26.1.21 in Abramowitz and Stegun (1970) with $n = T$ and $p = s_k d_k / s$.

Let X_k be a random variable that counts the number of terms of the k th homogeneous component g_k of g which is homogeneous of degree k in the variables x_1, \dots, x_{n-1} . Let us define the random variable $X = \sum_{k=0}^d X_k$ which counts the number of terms T_g of g .

Example 5. Let $n = 3, d = 6$ and $\alpha_3 = 1$. Below $g = f(x_3 = 1)$.

$$\begin{array}{cccccc}
 f = & \underbrace{1 + x_3^5}_{Y_0=2} & + \underbrace{2x_1x_3^4}_{Y_1=1} & + \underbrace{x_1x_2^2(3x_3 + 4x_3^2) + 5x_1^2x_2x_3^3}_{Y_3=3} & + \underbrace{x_1^2x_2^2(6x_3 + 7x_3^2)}_{Y_4=2} & + \underbrace{8x_1^3x_2^3}_{Y_6=1} \\
 & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \\
 g = & \underbrace{2}_{X_0=1} & + \underbrace{2x_1}_{X_1=1} & + \underbrace{7x_1x_2^2 + 5x_1^2x_2}_{X_3=2} & + \underbrace{13x_1^2x_2^2}_{X_4=1} & + \underbrace{8x_1^3x_2^3}_{X_6=1}
 \end{array}$$

So $Y = \sum_{k=0}^6 Y_k = 9$ and $X = \sum_{k=0}^6 X_k = 6$.

The expected number of terms of g is $E[X] = \sum_{k=0}^d E[X_k]$. We have

$$\begin{aligned}
 E[X_k] &= \sum_{i=0}^{s_k} i \Pr[X_k = i] = \sum_{i=0}^{s_k} i \sum_{j=0}^{s_k d_k} \Pr[X_k = i | Y_k = j] \Pr[Y_k = j] \\
 &= \sum_{j=0}^{s_k d_k} \Pr[Y_k = j] \sum_{i=0}^{s_k} i \Pr[X_k = i | Y_k = j].
 \end{aligned}$$

Our first aim is to find the conditional expectation

$$E[X_k | Y_k = j] = \sum_{i=0}^{s_k} i \Pr[X_k = i | Y_k = j].$$

To this end, let $M_k = \{\mathbf{m}_1, \dots, \mathbf{m}_{s_k}\}$ be the set of all monomials in x_1, \dots, x_{n-1} with homogeneous degree k . We have $|M_k| = s_k$. For $1 \leq i \leq s_k$ and $j > 0$, let A_i be the set of all non-zero polynomials in $\mathbb{Z}_p[x_1, \dots, x_n]$ with j terms that are homogeneous of total degree k in the variables x_1, \dots, x_{n-1} , have degree $< d_k$ in the variable x_n and do not include a term of the form $c\mathbf{m}_i x_n^r$ for any $0 \leq r < d_k$ for some non-zero $c \in \mathbb{Z}_p$. So using the table below, A_i is the set of all non-zero polynomials whose support does not contain any monomial from the i th row. Note that if $f_k \in A_i$ then $\#f(x_n = \alpha_n) \leq s_k - 1$.

	1	x_n	...	$x_n^{d_k-1}$
\mathbf{m}_1	\mathbf{m}_1	$\mathbf{m}_1 x_n$...	$\mathbf{m}_1 x_n^{d_k-1}$
\mathbf{m}_2	\mathbf{m}_2	$\mathbf{m}_2 x_n$...	$\mathbf{m}_2 x_n^{d_k-1}$
\vdots	\vdots	\vdots	\vdots	\vdots
\mathbf{m}_{s_k}	\mathbf{m}_{s_k}	$\mathbf{m}_{s_k} x_n$...	$\mathbf{m}_{s_k} x_n^{d_k-1}$

If f_k is the k th homogeneous component of f in the first $n - 1$ variables, then if no zero evaluation occurs in the coefficients of f_k in the variables x_n (as was assumed), we have

$$f_k \in \bigcup_{i=1}^{s_k} A_i \iff \#f_k(x_1, \dots, x_{n-1}, \alpha_n) \leq s_k - 1.$$

Example 6. Let $n = 3, k = 3, d_3 = 3, j = 4$. We have

$$M_k = \{\mathbf{m}_1 = x_1^3, \mathbf{m}_2 = x_1^2 x_2, \mathbf{m}_3 = x_1 x_2^2, \mathbf{m}_4 = x_2^3\},$$

with $s_k = 4$. Consider the polynomials

$$F = x_1 x_2^2 + x_2^3 x_3^2 + x_1^3 (x_3 + x_3^2) \in A_2, \quad G = x_1 x_2^2 x_3^2 + x_1^3 (1 + x_3 + x_3^2) \in A_2 \cap A_4.$$

So, $\#F(x_n = \alpha_n) \leq 4 - 1 = 3$ and $\#G(x_n = \alpha_n) \leq 4 - 2 = 2$.

Let us define

$$C_l := \bigcup_{i_1 < \dots < i_l} (A_{i_1} \cap A_{i_2} \dots \cap A_{i_l}) \text{ and } B_l := C_l - C_{l+1}$$

for $1 \leq l \leq s_k - 1$. Then C_l is the union of all possible intersections of the l -subsets of the collection $\Gamma = \{A_i, i = 1, \dots, s_k\}$. Observe that $C_l \supseteq C_{l+1}$, so $|B_l| = |C_l| - |C_{l+1}|$. (See Fig. 1.) Let us also define $B_{s_k} = C_{s_k} = \bigcap_{i=1}^{s_k} A_i$ and

$$b_l := |B_l| \text{ and } m_l := \sum_{i_1 < \dots < i_l} |A_{i_1} \cap A_{i_2} \dots \cap A_{i_l}| \text{ for } 1 \leq l \leq s_k,$$

so that $m_1 = \sum_{i=1}^{s_k} |A_i|$ and $m_2 = \sum_{1 \leq i < j \leq s_k} |A_i \cap A_j|$.

With this notation we have

$$f_k \in B_l \iff \#f_k(x_1, \dots, x_{n-1}, \alpha_n) = s_k - l.$$

Let $v_j := \binom{s_k d_k}{j}$ and $q := (p - 1)$. Assuming that no zero evaluation occurs, we have

$$\Pr[X_k = s_k - l \mid Y_k = j] = \frac{|B_l|}{q^j v_j}. \tag{2}$$

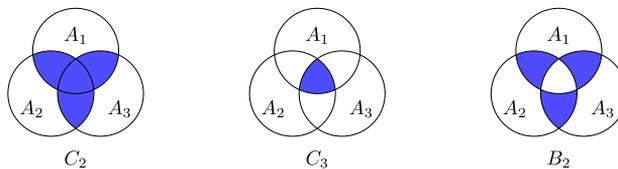


Fig. 1. Show sets C_2, C_3, B_2 in blue for three sets A_1, A_2, A_3 . (For interpretation of the colors in the figure, the reader is referred to the web version of this article.)

It can be seen by counting that

$$\Pr[X_k = l \mid Y_k = j] = v_j^{-1} \sum_{i=0}^l (-1)^i \binom{s_k - (l-i)}{i} \binom{s_k}{l-i} \binom{d_k(l-i)}{j}$$

But this formula is not easy to manipulate. So, to compute the expected value of X , we will follow the easier way described in Monagan and Tuncer (2016a).

We have $|A_i| = (p - q)^j \binom{s_k - 1}{j} d_k$ and $|A_i \cap A_l| = q^j \binom{s_k - 2}{j} d_k$ for $1 \leq i, l \leq s_k$ where $i \neq l$. It has been proven in Monagan and Tuncer (2016a) that $\sum_{i=1}^{s_k} i |B_i| = m_1$ and $\sum_{i=1}^{s_k} i^2 |B_i| = m_1 + 2m_2$. To find the expected value of X , let us first define $w_j := \binom{s_k - 1}{j} d_k$ and the random variable $Z_k := s_k - X_k$. Then $Z_k = i \iff X_k = s_k - i$. Recall that $v_j := \binom{s_k}{j} d_k$. Then we have

$$\sum_{i=1}^{s_k} i \Pr[Z_k = i \mid Y_k = j] \stackrel{(1)}{=} \sum_{i=1}^{s_k} i \frac{|B_i|}{q^j v_j} = \frac{\sum_{i=1}^{s_k} i |B_i|}{q^j v_j} = \frac{\sum_{i=1}^{s_k} |A_i|}{q^j v_j} = s_k \frac{w_j}{v_j}$$

Since $E[X_k \mid Y_k = j] = E[s_k - Z_k \mid Y_k = j] = s_k - E[Z_k \mid Y_k = j]$, we have

$$E[X_k \mid Y_k = j] = \sum_{i=0}^{s_k} i \Pr[X_k = i \mid Y_k = j] = s_k \left(1 - \frac{w_j}{v_j}\right)$$

To save some space let $y_{kj} := \Pr[Y_k = j]$. Then

$$\begin{aligned} E[X] &= \sum_{k=0}^d E[X_k] = \sum_{k=0}^d \sum_{j=0}^{s_k d_k} y_{kj} \sum_{i=0}^{s_k} i \Pr[X_k = i \mid Y_k = j] \\ &= \sum_{k=0}^d \sum_{j=0}^{s_k d_k} y_{kj} s_k \left(1 - \frac{w_j}{v_j}\right) = \sum_{k=0}^d \sum_{j=0}^{s_k d_k} y_{kj} s_k - \sum_{k=0}^d \sum_{j=0}^{s_k d_k} y_{kj} s_k \frac{w_j}{v_j} \\ &= \sum_{k=0}^d s_k \sum_{j=0}^{s_k d_k} y_{kj} - \sum_{k=0}^d \sum_{j=0}^{s_k d_k} \frac{1}{\binom{s}{T}} \binom{s_k d_k}{j} \binom{s - s_k d_k}{T - j} s_k \frac{\binom{(s_k - 1) d_k}{j}}{\binom{s_k d_k}{j}} \\ &= \sum_{k=0}^d s_k - \frac{1}{\binom{s}{T}} \sum_{k=0}^d s_k \sum_{j=0}^{s_k d_k} \binom{s - s_k d_k}{T - j} \binom{(s_k - 1) d_k}{j} \\ &= \sum_{k=0}^d s_k - \sum_{k=0}^d s_k \frac{\binom{s - d_k}{T}}{\binom{s}{T}} = \sum_{k=0}^d s_k \left(1 - \frac{\binom{s - d_k}{T}}{\binom{s}{T}}\right) \end{aligned}$$

Note that what we have done so far can easily be generalized when the number of evaluation points $m > 1$ and redefining s_k and d_k . For $0 < m < n$ let

$$g = f(x_1, \dots, x_{n-m}, x_{n-m+1} = \alpha_{n-m+1}, \dots, x_n = \alpha_n)$$

for m randomly chosen non-zero elements $\alpha_{n-m+1}, \dots, \alpha_n \in \mathbb{Z}_p$ and $s = \binom{n+d}{n}$, $s_k = \binom{n-m-1+k}{n-m-1}$ and $d_k = \binom{d-k+m}{m}$. If no zero evaluation occurs at the coefficients of f and we define the random variable $Y = \sum_{k=0}^d Y_k$ which counts the number of terms of f , then what we get is the conditional expectation

$$E[X \mid Y = T] = \sum_{k=0}^d s_k \left(1 - \frac{\binom{s - d_k}{T}}{\binom{s}{T}}\right) \tag{3}$$

From now on, to save some space, when it is clear from the context, we will use the notation $E[X]$ instead of $E[X \mid Y = T]$. Although it is not difficult to compute, this formula is not useful. In

order to have a smooth formulation in our complexity analysis, we want a good approximation. First, we observe

$$\binom{s-d_k}{T} / \binom{s}{T} = \left(1 - \frac{T}{s}\right) \left(1 - \frac{T}{s-1}\right) \cdots \left(1 - \frac{T}{s-d_k+1}\right).$$

For $0 \leq i < d_k$ we have $\left(1 - \frac{T}{s}\right) - \left(1 - \frac{T}{s-i}\right) = \frac{iT}{s(s-i)} < \frac{d_k T}{s(s-d_k)}$. Let $\gamma_i := \frac{iT/s}{s-i}$. Then

$$\prod_{i=0}^{d_k-1} \left(1 - \frac{T}{s-i}\right) = \prod_{i=0}^{d_k-1} \left(1 - \frac{T}{s} - \gamma_i\right) = \left(1 - \frac{T}{s}\right)^{d_k} + Er$$

where

$$Er = \sum_{l=1}^{d_k} (-1)^l \left(\sum_{0 \leq i_1 < \dots < i_l \leq d_k-1} \prod_{j=1}^l \gamma_{i_j} \right) \left(1 - \frac{T}{s}\right)^{d_k-l}.$$

Since

$$\prod_{i=1}^l \gamma_i < \left(\frac{d_k T/s}{s-d}\right)^l = \left(\frac{d_k}{s}\right)^l \left(\frac{T/s}{1-d_k/s}\right)^l \rightarrow 0 \text{ as } \frac{d_k}{s} \rightarrow 0$$

we see that $Er \rightarrow 0$ and hence the ratio $\binom{s-d_k}{T} / \binom{s}{T} \rightarrow \left(1 - \frac{T}{s}\right)^{d_k}$ as $\frac{d_k}{s} \rightarrow 0$.

Remark 7. From now on, unless indicated, whenever we use the symbol \approx or \lesssim we mean that in the calculation the approximation

$$\binom{s-d_k}{T} / \binom{s}{T} \approx (1-t_f)^{d_k} \tag{4}$$

is used (with error Er) where $t_f = T/s$ is the density ratio of f . When m is not close to n , since $s \in \mathcal{O}(n^d)$ and in the sparse case t_f is relatively small, the error Er is very close to zero not only asymptotically but also for practical values for n and d (see Example 8).

For a single evaluation, that is, $m = 1$, we expect

$$E[X] \approx \sum_{k=0}^d s_k \left(1 - (1-t_f)^{d_k}\right). \tag{5}$$

So, in the dense case where t_f is very close to 1, we expect approximately $\sum_{k=0}^d s_k$ many terms, i.e. most of the possible monomials in the variables x_1, \dots, x_{n-1} up to degree d . In the very sparse case where t_f is very close to zero, using the approximation $(1-t_f)^{d_k} \approx 1 - d_k t_f$, we expect approximately $t_f \sum_{k=0}^d s_k d_k = t_f s = T$ terms.

Equation (3) above is the expected number of terms $E[T_g]$ of g . Let γ be the number of all possible monomials in the variables x_1, \dots, x_{n-1} up to degree $d-1$, i.e. $\gamma = \binom{n+d-1}{n-1}$. Dividing the both sides of (3) by γ we get the expected density ratio

$$E[T_g] / \gamma = E[T_g / \gamma] \Rightarrow E[t_g] = 1 - \gamma^{-1} \sum_{k=0}^d s_k \frac{\binom{s-d_k}{st_f}}{\binom{s}{st_f}}. \tag{6}$$

So, we have an induced function $e_t : t_f \mapsto E[t_g]$. Using (6)

$$E[t_g] \approx 1 - \gamma^{-1} \sum_{k=0}^d s_k (1-t_f)^{d_k}. \tag{7}$$

Example 8. Table 1 below presents the results of experiments with 4 random polynomials f_1, f_2, f_3, f_4 with $n = 7$ variables and degree $d = 15$. T_{g_i} and t_{g_i} are the actual number of terms and the density ratio of each $g_i = f_i(x_n = \alpha_i)$. $E[t_{g_i}]$ and eT_{g_i} are the expected number of terms of g_i based on Eqs. (3) and (5) resp. $E[t_{g_i}]$ and et_{g_i} are the expected density ratio of g_i based on Eqs. (6) and (7) resp.

Table 1
Expected number of terms after evaluation.

	T_{f_i}	t_{f_i}	T_{g_i}	$E[T_{g_i}]$	eT_{g_i}	t_{g_i}	$E[t_{g_i}]$	et_{g_i}
f_1	17161	.100625	14356	14370.47	14370.36	.264558	.264825	.264823
f_2	19887	.116609	16196	16221.84	16221.73	.298466	.298943	.298941
f_3	29845	.174998	22303	22211.09	22210.96	.411009	.409315	.409313
f_4	39823	.233505	27244	27199.53	27199.41	.502063	.501244	.501242

Note that the polynomial function $e_t(y) = 1 - \gamma^{-1} \sum_{k=0}^d s_k (1 - y)^{dk}$ is strictly increasing on the interval $[0, 1]$, since $e'_t(y) > 0$ on the interval $[0, 1]$. Also $e_t(0) = 0$ and $e_t(1) = 1$. For a given $0 \leq y_0 \leq 1$, consider the function $h(y) := e_t(y) - y_0$. We have $h(0) \leq 0$ and $h' > 0$ on $[0, 1]$. Hence $h(y)$ has only 1 real root in $[0, 1]$. This helps us to estimate T_f when we're given only T_g . Here is one example in the reverse direction.

Example 9. We call Maple's `randpoly` command to give a random sparse polynomial of degree 15 in 7 variables. It gives us a polynomial f with $T_f = 25050$. Suppose we don't know T_f . Then we choose a random point α and evaluate $g = f(x_n = \alpha)$. We compute $T_g = 19395$. Then we compute $t_g = 19395 / \binom{7+15}{15} \approx 0.3574192835$ and $\gamma = \binom{7+15}{15}^{-1}$. Using (6) we seek for the solutions of the polynomial equation

$$0.3574192835 = 1 - \gamma^{-1} \sum_{k=0}^{15} \binom{5+k}{k} (1-y)^{16-k}.$$

This polynomial equation has only one real root $y = 0.1461603065$ in $[0, 1]$. So we guess $E[t_f] \approx 0.1461603065$. The actual density ratio is $t_f = 25050 / \binom{7+15}{15} = 0.1461089220$. Our guess implies $E[T_f] \approx t_f \binom{7+15}{7} = 24926$, whereas $T_f = 25050$. We repeated Example 9 with 4 random polynomials f_i where $g_i = f_i(x_n = \alpha_i)$. The results of the experiments are in Table 2.

Table 2
Expected number of terms before evaluation.

	T_{g_i}	t_{g_i}	$E[t_{f_i}]$	t_{f_i}	$E[T_{f_i}]$	T_{f_i}
f_1	14967	.2758182220	.1056824733	.1052983394	18023	17958
f_2	14597	.2689997051	.1025359262	.1020792288	17486	17409
f_3	14439	.2660880142	.1012024458	.1008713294	17259	17203
f_4	14375	.2649085950	.1006640188	.1005605592	17167	17150

Finally, following the notation in the beginning of the section, if some of the $c_i(\alpha_n) = 0$ for $1 \leq i \leq t$, then we consider $\tilde{f} = \sum_{k=0}^{t_{ik}} c_{ik}(x_n) \mathbf{m}_{ik}$ where $\text{Supp}(\tilde{f}) \subseteq \text{Supp}(f)$ and $c_{ik}(\alpha_n) = 0$. Then

$$E[T_f] = E[T_{f-\tilde{f}}] \leq \sum_{k=0}^d s_k \left(1 - (1 - t_f)^{dk} \right)$$

So what we have found is an upper bound for $E[X]$. On the other hand since we choose $\alpha_n \neq 0$ a non-zero monomial does not evaluate to zero, that is, if $\#c_i(x_n) = 1$ then $\mathbf{m}_i c_i(\alpha_n) \neq 0$. So we should apply the zero evaluation probability only to the terms $\mathbf{m}_i c_i(x_n)$ with $\#c_i(x_n) \geq 2$. Then, for given $f \in \mathbb{Z}_p[x_1, \dots, x_n]$ of degree $\leq d$ with T terms, the probability that zero evaluation occurs for a randomly chosen non-zero $\alpha_n \in \mathbb{Z}_p$ is $\leq \frac{dT}{2(p-1)}$. We sum up our observations so far in Section 4 by Lemma 10 equations (8), (9) and (10).

Lemma 10. Let p be a big prime and $f \in \mathbb{Z}_p[x_1, \dots, x_n]$ be a random multivariate polynomial of degree of at most d that has T_f non-zero terms. Also let $0 < m < n$ and

$$g = f(x_1, \dots, x_{n-m}, x_{n-m+1} = \alpha_{n-m+1}, \dots, x_n = \alpha_n)$$

for m randomly chosen non-zero elements $\alpha_{n-m+1}, \dots, \alpha_n \in \mathbb{Z}_p$. Let T_g be the number of terms of g and T_{g_k} be the number of monomials in g that are homogeneous of degree k in the variables x_1, \dots, x_{n-m} . Also let $s = \binom{n+d}{n}$, $s_k = \binom{n-m-1+k}{n-m-1}$, $\gamma = \binom{n-m+d}{n-m}$ and $d_k = \binom{d-k+m}{m}$. Then

$$E[T_g] \leq \sum_{k=0}^d s_k \left(1 - \frac{\binom{s-d_k}{T_f}}{\binom{s}{T_f}} \right). \tag{8}$$

Let the density of f , $t_f = T_f/s$. Equation (8) implies that if $\frac{d_k}{s} \rightarrow 0$, then with probability $\geq 1 - \frac{dT_f}{2(p-1)}$ one has

$$E[T_g] \approx \sum_{k=0}^d s_k (1 - (1 - t_f)^{d_k}). \tag{9}$$

Equation (9) implies that with probability $\geq 1 - \frac{dT_f}{2(p-1)}$

$$E[t_g] \approx 1 - \gamma^{-1} \sum_{k=0}^d s_k (1 - t_f)^{d_k}. \tag{10}$$

4.1. On Zippel's assumption

The sparse interpolation idea and the first gcd algorithm to use sparse interpolation were introduced and analyzed by Zippel in his research paper (Zippel, 1979). The goal polynomial (the gcd) is $P(x_1, \dots, x_n)$ and the starting point is $\vec{a} = (a_1, \dots, a_n)$. According to our notation, $T_{f_{n-i}}$ denotes the number of terms of the polynomial $P(x_1, \dots, x_i, a_{i+1}, \dots, a_n)$. In subsection 3.2 of Zippel (1979) after computing a sum which depends on the values $T_{f_{n-i}}$, Zippel claims “We need to make some assumptions about the structure of $T_{f_{n-i}}$ to get anything meaningful out of this. We will assume that the ratio of the terms $T_{f_{n-i}}/T_{f_{n-i+1}}$ is a constant k .”³

Our observations in this section show that this assumption is wrong. To see a more accurate bound on the expected ratio of the subsequent number of terms, let us denote by $d_k^{(i)} = \binom{d-k+i}{d-k}$, $s^{(i)} = \binom{n-i+d}{n-i}$, $s_k^{(i)} = \binom{n-i+k-1}{n-i-1}$, $r_k^{(i)} = \binom{s-d_k^{(i)}}{T} / \binom{s}{T}$ and $\beta_k^{(i)} = 1 - r_k^{(i)}$. Let

$$f_i = f(x_1, \dots, x_{n-i}, x_{n-i+1} = \alpha_{n-i+1}, \dots, x_n = \alpha_n)$$

be the polynomial in $n - i$ variables after i random evaluations. According to Lemma 10 $E[T_{f_i}] = \sum_{k=0}^d s_k^{(i)} \beta_k^{(i)}$. Our aim is to find an upper and lower bound for

$$\frac{E[T_{f_i}]}{E[T_{f_{i+1}}]} = \frac{\sum_{k=0}^d s_k^{(i)} \beta_k^{(i)}}{\sum_{k=0}^d s_k^{(i+1)} \beta_k^{(i+1)}}. \tag{11}$$

Observe that

$$d_k^{(i+1)} > d_k^{(i)} \Rightarrow s - d_k^{(i+1)} < s - d_k^{(i)} \Rightarrow r_k^{(i+1)} < r_k^{(i)} \Rightarrow \beta_k^{(i+1)} > \beta_k^{(i)}.$$

³ Zippel (1979) uses the notation t_i for $T_{f_{n-i}}$. Since we use the symbol t for the density, we use our notation as to not confuse the reader.

Then

$$\frac{E[T_{f_i}]}{E[T_{f_{i+1}}]} = \frac{\sum_{k=0}^d s_k^{(i)} \beta_k^{(i)}}{\sum_{k=0}^d s_k^{(i+1)} \beta_k^{(i+1)}} < \frac{\sum_{k=0}^d s_k^{(i)} \beta_k^{(i)}}{\sum_{k=0}^d s_k^{(i+1)} \beta_k^{(i)}} \leq \max_k \left\{ \frac{s_k^{(i)}}{s_k^{(i+1)}} \right\}.$$

We have

$$\frac{s_k^{(i)}}{s_k^{(i+1)}} = \frac{n-i+k-1}{n-i-1} = 1 + \frac{k}{n-i-1} \leq 1 + \frac{d}{n-i-1}.$$

Our next aim is to show that $E[t_{f_{i+1}}] \geq E[t_{f_i}]$: we have

$$E[t_{f_i}] = 1 - \sum_{k=0}^d \frac{s_k^{(i)}}{s^{(i)}} r_k^{(i)} = 1 - \sum_{k=0}^d \frac{\binom{n-i+k-1}{n-i-1}}{\binom{n-i+d}{n-i}} \frac{\binom{s-d_k^{(i)}}{T}}{\binom{s}{T}} = 1 - \sum_{k=0}^d \frac{\binom{n-i+k-1}{n-i-1}}{\binom{s}{T}} \frac{\binom{s-d_k^{(i)}}{n-i+d}}{\binom{s}{n-i}}$$

Let $v_k^{(i)} = \binom{n-i+k-1}{n-i-1} / \binom{s}{T}$ and $w_k^{(i)} = \binom{s-d_k^{(i)}}{T} / \binom{n-i+d}{n-i}$. Then $v_k^{(i+1)} / v_k^{(i)} < 1$ and $w_k^{(i+1)} / w_k^{(i)} < 1$. So $\sum_{k=0}^d v_k^{(i)} w_k^{(i)}$ decreases and hence $E[t_{f_i}]$ increases as i increases, i.e., we expect an increase in the density ratio after each evaluation. On the other hand,

$$E[T_{f_i}] = E[t_{f_i}] \binom{n-i+d}{n-i} = E[t_{f_i}] \frac{n-i+d}{n-i} \binom{n-(i+1)+d}{n-(i+1)} \geq E[t_{f_i}] \frac{n-i+d}{n-i} E[T_{f_{i+1}}].$$

It follows that

$$\frac{E[T_{f_i}]}{E[T_{f_{i+1}}]} \geq E[t_{f_i}] \left(1 + \frac{d}{n-i} \right).$$

Hence

$$E[t_{f_i}] \left(1 + \frac{d}{n-i} \right) \leq \frac{E[T_{f_i}]}{E[T_{f_{i+1}}]} \leq 1 + \frac{d}{n-i-1}.$$

Now, since each of $E[t_{f_i}]$, $1 + \frac{d}{n-i}$, $1 + \frac{d}{n-i-1}$ increases as i increases we expect an increase in the ratio $E[T_{f_i}] / E[T_{f_{i+1}}]$.

This means we expect that the ratio $T_{f_{n-i}} / T_{f_{n-i+1}}$ increases as i decreases, i.e., after each evaluation we expect an increase in the ratio of subsequent number of terms. See Example 11 for a sparse case and Example 12 for a (relatively) dense case.

Example 11. (Sparse case with $t_f = 0.000044$). Table 3 below shows the result of a random experiment where $p = 2^{31} - 1$, $n = 12$, $d = 20$, $T_f = 10^4$, $t_f = 0.000044$ and $f_i := f_{i-1}(x_{n-i+1} = \alpha_{n-i+1})$ with $f_0 = f$, for randomly chosen non-zero α_i 's in \mathbb{Z}_p . Observe that when we evaluate the first 4 variables the number of terms didn't drop significantly.

Table 3
The ratio of subsequent number of terms (sparse case): T_{f_i} decreases slowly until $i = 5$.

i	T_{f_i}	$E[T_{f_i}]$	t_{f_i}	$t_{f_i}(1 + \frac{d}{n-i})$	$T_{f_i}/T_{f_{i+1}}$	$1 + \frac{d}{n-i-1}$
0	10000	10000	0.00004	0.00012	1.0000	2.8182
1	10000	9999.32	0.00012	0.00033	1.0006	3.0000
2	9994	9995.19	0.00033	0.00100	1.0025	3.2222
3	9969	9971.08	0.00100	0.00321	1.0135	3.5000
4	9836	9837.31	0.00316	0.01108	1.0686	3.8571
5	9205	9200.70	0.01037	0.03998	1.2767	4.3333
6	7210	7219.37	0.03132	0.13570	1.7470	5.0000
7	4127	4144.61	0.09710	0.48548	2.4435	6.0000
8	1689	1690.52	0.23090	1.38540	3.3512	7.6667
9	504	497.93	0.37895	2.90530	4.8932	11.000
10	103	104.50	0.54210	5.96310	7.3571	21.000

Example 12. (Dense case with $t_f = 0.1$). Table 4 below shows the result of a random experiment where $p = 2^{31} - 1$, $n = 7$, $d = 13$, $T_f = 7752$, $t_f = 0.1$ where $f_i := f_{i-1}(x_{n-i+1} = \alpha_{n-i+1})$ with $f_0 = f$, for randomly chosen non-zero α_i 's in \mathbb{Z}_p . Observe that the number of terms dropped by about 10% after the first evaluation.

Table 4

The ratio of subsequent number of terms (dense case): T_{f_i} decreases immediately.

i	T_{f_i}	$E[T_{f_i}]$	t_{f_i}	$t_{f_i}(1 + \frac{d}{n-i})$	$T_{f_i}/T_{f_{i+1}}$	$1 + \frac{d}{n-i-1}$
0	7752	7752	0.10	0.28	1.17	3.16
1	6670	6643.44	0.24	0.77	1.76	3.60
2	3774	3800.14	0.44	1.58	2.70	4.25
3	1398	1409.83	0.58	2.49	3.65	5.33
4	383	394.03	0.68	3.64	4.78	7.50
5	80	81.14	0.76	5.71	6.66	14

The dominating term of the complexity analysis of Zippel is $\sum_{i=1}^n c_1 d T_{f_{n-i+1}}^3$ where c_1 is a constant. He assumes $T_{f_{n-i}}/T_{f_{n-i+1}} = k \Rightarrow T_{f_{n-i}} = T_{f_n} k^i$. It follows that

$$\sum_{i=1}^n c_1 d T_{f_{n-i+1}}^3 = c_1 d \sum_{i=1}^n T_{f_{n-i+1}}^3 = c_1 d T_{f_n}^3 \sum_{i=1}^n k^{3i} = c_1 d k^3 \frac{(k^{3n} - 1) T_{f_n}^3}{k^3 - 1}.$$

Since $T_f = T_{f_0} = T_{f_n} k^n$, if k is large in comparison to 1 then this sum approaches $c_1 d T_f^3$ but if k is very close to 1 then this sum approaches to $c_1 n d T_f^3$. Then he concludes that if $T_f \gg d$ or n , the dominant behavior is $\mathcal{O}(T_f^3)$.

The case where k is very close to 1 (where Zippel has a very sparse case in mind) is the worst case analysis. One can construct such an example. More precisely, Zippel's analysis shows that the complexity for the worst case is $\mathcal{O}(n d T_f^3)$ and for the average case (where he assumes that “ k is large in comparison to 1”) the complexity is $\mathcal{O}(d T_f^3)$. Below we will show that this is not true and prove that even for the average case the expected complexity is $\mathcal{O}(n d T_f^3)$ for a sparse gcd computation.

Example 11 (the sparse case) shows that after 5 evaluations the number of terms is still 90% of T_f . See column T_f . This means the cost of each interpolation of the last few variables in Zippel's algorithm is the same and equal to $\mathcal{O}(d T_f^3)$. However in Example 12 (the relatively dense case) the number of terms starts to drop right away. Proposition 13 below qualifies this behavior and makes the observation of Example 11 precise.

Proposition 13. Following the notation above, let $\mathcal{I} = \{i \in \mathbb{N} \mid t_f \leq 1/(i^{\frac{d}{p-1}}) \text{ and } i \leq n\}$. Then with probability $\geq 1 - \frac{d T_f}{2(p-1)}$, one has

- (i) $\frac{E[T_{f_i}]}{T_f} \geq 1 - t_f^2$ for $i \in \mathcal{I}$,
- (ii) if $n \leq d$, then $|\mathcal{I}| \geq \max\{1, \lceil n - \log_r T_f \rceil\}$ where $r = 1 + \frac{d}{n}$.

The proof of Proposition 13 is given in Appendix C. For Example 11, $\max\{1, \lceil n - \log_r T_f \rceil\} = \max\{1, \lceil 12 - \log_{2.6} 10^4 \rceil\} = \max\{1, 3\} = 3$ whereas $|\mathcal{I}| = 5$. For Example 12, $|\mathcal{I}| = 1$ whereas $\max\{1, \lceil n - \log_r T_f \rceil\} = \max\{1, \lceil 7 - \log_{2.86} 7752 \rceil\} = \max\{1, -1\} = 1$.

Corollary 14. Following the notation above, the average complexity of the sparse gcd algorithm of Zippel is $\Omega(|\mathcal{I}| d T_f^3)$. If $n \leq d$ then the average complexity is in $\Omega(\max\{1, \lceil n - \log_r T_f \rceil\} d T_f^3)$ where $r = 1 + \frac{d}{n}$.

Remark 15. According to Proposition 13(i), when t_f is small, on average we expect that $T_{f_i} \approx T_f$ for $i \in \mathcal{I}$, i.e. for at least $|\mathcal{I}|$ many steps, we don't expect a significant decrease in the number of terms.

Note that as t_f gets smaller, i.e., the inputs gets sparser, $|\mathcal{I}|$ gets closer to n . Also, in practice $n \leq d$ and as T_f get smaller $\log_r T_f$ gets smaller and according to Proposition 13(ii) $|\mathcal{I}| \geq \lceil n - \log_r T_f \rceil$ gets closer to n . This means for the sparse case the average complexity is in $\mathcal{O}(ndT_f^3)$. Thus, the common perception that in the sparse interpolation most of the work is done when recovering the last variable x_n is not true: For most sparse examples, the work done to recover $x_{n/2}, x_{n/2+1}, \dots, x_{n-1}$ is the same as x_n .

5. The expected number of terms of Taylor coefficients

Consider the Taylor expansion of $f_j, g_j \in \mathbb{Z}_p[x_1, \dots, x_n]$ about $x_n = \alpha_n$ for $0 \neq \alpha_n \in \mathbb{Z}_p$. Let $f_j = \sum_{i=0}^{d_n} f_{ji}(x_n - \alpha_n)^i$ and $g_j = \sum_{i=0}^{d_n} g_{ji}(x_n - \alpha_n)^i$ where $f_{ji}, g_{ji} \in \mathbb{Z}_p[x_1, \dots, x_{n-1}]$. In the i th iteration of the for loop of the j th step of MTSHL (Algorithm 5) one solves the MDP $f_{ji}g_{j0} + g_{ji}f_{j0} = c_{ji}$ to compute f_{ji} and g_{ji} for $1 \leq i \leq d_n$. The cost of MDP depends on the sizes of the polynomials f_{ji}, g_{ji} and c_{ji} .

To make our complexity analysis as precise as possible, in this section we will compute theoretical estimations for the expected sizes of the Taylor coefficients f_j and the upper bounds for $E[T_{f_j}]$ of a randomly chosen $f \in \mathbb{Z}_p[x_1, \dots, x_n]$ where $f = \sum_{i=0}^{d_n} f_j(x_n - \alpha_n)^j$ for a randomly chosen non-zero element $\alpha_n \in \mathbb{Z}_p$ and p is a big prime. We will confirm our theoretical estimations by experimental data.

In the sequel we will use the notation $\#f$ and T_f interchangeably. For a random non-zero $\alpha_n \in \mathbb{Z}_p$, consider $f = \sum_{j=0}^{d_n} f_j(x_n - \alpha_n)^j$ where each $f_j \in \mathbb{Z}_p[x_1, \dots, x_{n-1}]$. We expect $T_{f_{j+1}} \leq T_{f_j}$, that is, the size of the Taylor coefficients f_j decrease as j increases.

As a first step to find an upper bound on $E[T_{f_j}]$, we have the following Lemma.

Lemma 16. *Let $0 < d < p$ and $n > 0$. Then following the notation above, the probability of occurrence of each monomial in the support of $f' = \frac{\partial}{\partial x_n} f$ is the same.*

Proof. Let $\mathbf{m}' = cx_1^{\beta_1} \dots x_n^{\beta_n} \in \text{Supp}(f')$ where $\beta_1 + \dots + \beta_n \leq d - 1$. Then any monomial of the form $\mathbf{m} = (\beta_n + 1)^{-1} cx_1^{\beta_1} \dots x_n^{\beta_n+1} + \mathbf{n}$ where \mathbf{n} is a monomial of degree $\leq d$ which does not contain the variable x_n lies over \mathbf{m}' . We have $\beta_1 + \dots + (\beta_n + 1) \leq d$. On the other hand, for $\mathbf{m} = cx_1^{\beta_1} \dots x_n^{\beta_n} \in \text{Supp}(f)$, one has $\frac{\partial}{\partial x_n} \mathbf{m} = c\beta_n x_1^{\beta_1} \dots x_n^{\beta_n-1} = 0 \iff p | c\beta_n \iff p | \beta_n$. So if $d < p$ we have $\frac{\partial}{\partial x_n} \mathbf{m} = 0 \iff \mathbf{m}$ does not contain the variable x_n , i.e., $\beta_n = 0$. Therefore the number of monomials lying over each distinct monomial in the support of f' is the same and equal to $(p - 1)^\gamma + 1$ where $\gamma = \binom{n+d-1}{n}$. Since f is random, this implies that the probability of occurrence of each monomial in the support of f' is the same. \square

After differentiation, monomials which do not contain the variable x_n in f will disappear. Since the expected number of them is $= t_f \binom{n-1+d}{n-1}$, we expect

$$E[\#f'] = T_f - t_f \binom{n-1+d}{n-1}.$$

What about the density ratio $t_{f'}$ of f' ? We have

Lemma 17. *Following the notation above $E[t_{f'}] = t_f$.*

Proof.

$$\begin{aligned} E[t_{f'}] &= \left(T_f - t_f \binom{n-1+d}{n-1} \right) / \binom{n+d-1}{n} \\ &= t_f \left(\binom{n+d}{n} - \binom{n-1+d}{n-1} \right) / \binom{n+d-1}{n} \end{aligned}$$

$$\begin{aligned}
 &= t_f \left(\frac{n+d}{n} \binom{n+d-1}{n-1} - \binom{n-1+d}{n-1} \right) / \binom{n+d-1}{n} \\
 &= t_f \binom{n+d-1}{n-1} / \frac{n}{d} \binom{n+d-1}{d-1} = t_f \binom{n+d-1}{n-1} / \binom{n+d-1}{n-1} = t_f. \quad \square
 \end{aligned}$$

For simplicity let us assume that $p > j$. We have $f_j = \frac{1}{j!} \frac{\partial}{\partial x_n^j} f(x_n = \alpha)$. Also $f^{(j)} := \frac{\partial}{\partial x_n^j} f$ is of degree $\leq d_j := d - j$. Using Lemma 16 and 17 repeatedly,

$$E[f_j] \leq E[\#f^{(j)}] = E[t_{f^{(j)}}] \binom{n+d-j}{n} = t_f \binom{n+d-j}{n}.$$

It follows that

$$E[t_{f_j}] = E[f_j] / \binom{n+d-j}{n} \leq t_f.$$

We sum up the observations of this section in such a way that it will be helpful for the next sections.

Lemma 18. Let p be a big prime and $f_j \in \mathbb{Z}_p[x_1, \dots, x_j]$ be a multivariate polynomial of total degree $\leq d_j$ that has T_{f_j} non-zero terms. For a randomly chosen non-zero element $\alpha_j \in \mathbb{Z}_p$, consider $f_j = \sum_{i=0}^{d_j} f_{ji}(x_j - \alpha_j)^i$ where $f_{ji} \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$. Let $t_{f_j} = T_{f_j} / \binom{j+d_j}{j}$. Then

$$E[T_{f_{ji}}] \leq t_{f_j} \binom{j+d_j-i}{j} \text{ and } E[t_{f_{ji}}] \leq t_{f_j} \frac{j+d_j-i}{j}. \tag{12}$$

In the detailed complexity analysis of Algorithm 5 MTSHL, to determine the cost of the multiplication $f_j \times g_j$ in Step 15, we need to estimate the expected number of terms of the polynomials f_j and g_j which are computed in Step 14. In the k th iteration in the for loop, let us call the updated polynomials $f_j^{(k)}$ and $g_j^{(k)}$. Consider $f_j^{(k)}$. Let $f_j = \sum_{i=0}^{d_j} f_{ji}(x_j - \alpha_j)^i$ be the actual factor computed by Algorithm 5. Thus

$$f_j^{(k)} = \sum_{i=0}^k f_{ji}(x_j - \alpha_j)^i = f_j^{(k-1)} + f_{jk}(x_j - \alpha_j)^k$$

and we wish to bound $E[\#f_j^{(k)}]$ the expected size of the expanded form of $f_j^{(k)}$.

MTSHL assumes that (see Section 3.2) $\text{Supp}(f_{j,i+1}) \subseteq \text{Supp}(f_{ji})$. If this assumption holds, then when we expand $f_{jk}(x_j - \alpha_j)^k$, the monomials appearing in $f_{ji}x_j^k$ bring new terms to $f_j^{(k)}$. The rest combine with terms in $f_j^{(k-1)}$. Thus $E[\#f_j^{(k)}] \leq \sum_{i=0}^k E[\#f_{ji}]$. Applying Lemma 18

$$\begin{aligned}
 E[\#f_j^{(k)}] &\leq \sum_{i=0}^k t_{f_j} \binom{j+d_{ji}}{j} < \sum_{i=0}^d t_{f_j} \binom{j+d_{ji}}{j} = t_{f_j} \binom{j+d+1}{d} = \frac{j+d+1}{j+1} T_{f_j} \\
 &< (1 + \frac{d}{j}) T_{f_j}
 \end{aligned}$$

In Example 19 below, $j = 7, d_j = 13, T_{f_j} = 7752$. We have $(1 + \frac{d}{j})T_{f_j} = 22205.8$ which bounds all the numbers (the size of f_j^k) in the third column.

Example 19. Table 5 below shows the result of a random experiment where $p = 2^{31} - 1, j = 7, d_j = 13, T_{f_j} = 7752$. In Table 5, $T_{f_{ji}}, t_{f_{ji}}$ and $t_{f_j^{(i)}}$ are the actual values. The ratios in the fourth column show why the strong SHL assumption is useful. Also shown is the expected number of terms $E[T_{f_{ji}}]$ of f_{ji} , the bound $bT_{f_{ji}}$ on the expected number of terms of f_{ji} , and the bound $bt_{f_{ji}}$ on the density ratio of f_{ji} , which are based on (5) and (12) resp.

Table 5
The bounds on the expected number of terms and the density ratio.

i	$T_{f_{ji}}$	$\sum_{l=0}^i T_{f_{jl}}$	$\frac{T_{f_{ji-1}}}{T_{f_{ji}}}$	$E[T_{f_{ji}}]$	$bT_{f_{ji}}$	$t_{f_j^{(i)}}$	$t_{f_{ji}}$	$bt_{f_{ji}}$
0	6651	6651	–	6643.345	7752	0.09	0.085	0.285
1	4343	10994	1.53	4366.828	5038.8	0.1	0.086	0.271
2	2773	13767	1.57	2789.364	3182.4	0.09	0.088	0.257
3	1722	15489	1.61	1724.183	1944.8	0.10	0.088	0.242
4	977	16466	1.76	1025.981	1144.0	0.10	0.092	0.228
5	564	17030	1.73	583.867	643.5	0.10	0.093	0.214
6	306	17336	1.84	315.075	343.2	0.10	0.094	0.200
7	150	17486	2.04	159.417	171.6	0.10	0.103	0.185
8	68	17554	2.21	74.463	79.2	0.10	0.104	0.171
9	26	17580	2.62	31.403	33.0	0.10	0.127	0.157
10	12	17592	2.17	11.559	12.0	0.05	0.125	0.142
11	3	17595	4.00	3.511	3.6	0.12	0.111	0.128
12	1	17596	3.00	0.790	0.8	1	0.112	0.114

6. The complexity of the MDP

Let p be a big prime and $u, w, h \in \mathbb{Z}_p[x_1, \dots, x_n]$ where u, w are monic in x_1 . Suppose we are trying to solve the MDP (which satisfies the MDP conditions)

$$D := fu + gw = h \tag{13}$$

to find the unique solution pair (f, g) via sparse interpolation as described in Section 2. Let d be a total degree bound for f, g, u, w, h . Our aim in this section is to estimate the expected complexity of solving (13). Suppose the solution-form of f is

$$\sigma_f = \sum_{i+j \leq d} c_{ij}(x_3, \dots, x_n)x_1^i x_2^j \text{ where } c_{ij} = \sum_{l=1}^{m_{ij}} c_{ijl}x_3^{\gamma_{3l}} \dots x_n^{\gamma_{nl}} \text{ with } c_{ijl} \in \mathbb{Z}_p \setminus \{0\}.$$

Let $m = \max m_{ij}$. Then in sparse interpolation the first step is to choose a random $(\beta_3, \dots, \beta_n) \in (\mathbb{Z}_p \setminus \{0\})^{n-2}$ and solve bivariate MDP's

$$D_r := \tilde{f} \cdot u(x_1, x_2, \beta_3^r, \dots, \beta_n^r) + \tilde{g} \cdot w(x_1, x_2, \beta_3^r, \dots, \beta_n^r) = h(x_1, x_2, \beta_3^r, \dots, \beta_n^r)$$

for $r = 1, \dots, m$ where $(\tilde{f}, \tilde{g}) \in \mathbb{Z}_p[x_1, x_2]^2$ is to be solved.

As before let $s = \binom{n+d}{n}$, $r = \frac{n}{n+d}$, $s_k = \binom{n-2+k}{n-2}$ and $d_k = d - k + 1$ for $0 \leq k \leq d$. Suppose that the solution form σ_f of f is correct. Then the expected number of monomials of the form $x_3^{\alpha_3} \dots x_n^{\alpha_n} x_1^i x_2^j$ in $\text{Supp}(f)$ is $t_f \binom{n-2+d-k}{n-2} = t_f s_{d-k}$ when $i + j = k$. So we expect $\#c_{ij} = t_f s_{d-k}$. When $i = j = 0$, i.e. the number of monomials that are in the variables x_3, \dots, x_n in $\text{Supp}(f)$ is expected to be greatest, therefore the expected number of evaluations is $m = t_f s_d$. At this point we remark that

$$t_f s_d = T_f \frac{n(n-1)}{(n+d)(n+d-1)} \leq T_f \left(\frac{n}{n+d}\right)^2 = T_f r^2.$$

If d is big and T_f is small, $T_f r^2 < 1$ is possible. However the algorithm always makes at least one evaluation and hence calls BDP at least once, so we should use $m = \lceil t_f s_d \rceil$.

Let $T = (T_f + T_u + T_w + T_h)$. (We are evaluating σ_f too, to get the linear system of equations in c_{ijl} .) Then according to Section 2.4 the total cost C_E of the consecutive evaluations is bounded above by

$$\begin{aligned} C_E &\leq \# \text{of terms} \times (\# \text{of evaluations} + n - 3) + (n - 2)d \\ &\approx (T_f + T_u + T_w + T_h) (T_f \frac{s_d}{s} + 1 + n - 3) + (n - 2)d \\ &\leq T(\lceil T_f r^2 \rceil + n) + nd \end{aligned}$$

Finally suppose that the guessed solution-form σ_f of f is wrong. Then the solution to f that the sparse interpolation routine computes will be wrong. Since the solution to the MDP is unique as long as the MDP conditions are satisfied, then we will have $w \nmid h - fu$. So, in the sparse interpolation a possible failure, i.e. a possible false assumption is detected. In this case the cost of sparse division may increase (we don't consider this).

Theorem 20. *Let p be a big prime and $u, w, h \in \mathbb{Z}_p[x_1, \dots, x_n]$ where u, w are monic in x_1 . If the solution-form σ_f is true, then the number of arithmetic operations in \mathbb{Z}_p for solving the MDP $fu + gw = h$ (which satisfies the MDP conditions) to find the unique solution pair (f, g) via sparse interpolation as described in Section 2 is in*

$$O\left(T\lceil T_f r^2 \rceil + nT + nd + \lceil T_f r^2 \rceil d^3 + T_f^2 r^2 + T_f T_u + T_w T_g\right)$$

where d is a total degree bound for $f, g, u, w, h, r = \frac{n}{n+d}$, and $T = T_f + T_u + T_w + T_h$.

7. The complexity of MTSHL

For $j \geq 3$, the aim of MTSHL is to reach the factorization $a_j = f_j g_j \in \mathbb{Z}_p[x_1, \dots, x_j]$ from the knowledge of the previous factorization $a_{j-1} = f_{j-1} g_{j-1} \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$.

This task is accomplished by solving at most $\max(\deg_{x_j} f_j, \deg_{x_j} g_j)$ many MDPs whose complexity is investigated in the previous section. By using the observations developed in sections 3, 4, 5 and 6, the average complexity of MTSHL is given in Theorem 21 below. The proof is given in Appendix D. Before reading the details of the proof, we suggest the reader read the concrete example in the Appendix A to be able to follow the rest of discussion in Appendix D.

Theorem 21. *Let T_h denote the number of non-zero terms of a polynomial h and $a = fg \in \mathbb{Z}_p[x_1, \dots, x_n]$ with f, g monic in x_1 with $T_f \leq T_g$. Let $d = \deg(a), r = \frac{n}{n+d}$, and p be a big prime with $p \gg d$ and $p \gg T_f$. Then with the probability of failure*

$$< (n - 2)d^2 T_f \frac{d^2 + (d + 1)T_f}{p - 2d + 1},$$

the expected complexity of Algorithm 5 (MTSHL) to recover the factors f, g via is

$$O\left(\frac{n^2}{d} T_f T_a + n d T_a + n^2 d^2 T_g + n d^4 + d^3 T_f T_g\right).$$

The first two terms $(n^2/d)T_f T_a$ and ndT_a are for doing the evaluations in Step 8 of Algorithm 4. The second two contributions $n^2 d^2 T_g$ and nd^4 come from using Algorithm 6 to solve the bivariate diophantine equations in Step 9 of Algorithm 4. The last term $d^3 T_f T_g$ is for computing the error in Step 15 of Algorithm 5.

If we fix n, T_f and T_g and increase d so that the polynomials get sparser and the evaluation cost decreases, the error computation dominates. If we fix d and n and increase T_f, T_g , and T_a , the evaluation cost dominates. We will illustrate this in our experiments.

8. Some timing data

We implemented MTSHL in Maple with two key parts, BDP (see Section 2.3) and the evaluation routine (see Section 2.4) coded in C. To compare our algorithms to Wang's, we first factored the determinants of Toeplitz and Cyclic matrices of different sizes as concrete examples. These are dense problems where Wang's algorithm should fare well in comparison with our sparse algorithm. Then we generated random sparse examples.

We have also included a comparison of Maple's factorization timings with Singular and Magma to be sure that the main gain by MTSHL is independent of implementation of Wang's algorithm. For

multivariate factorization Maple, Singular and Magma all use Wang’s MHL following the presentation in Geddes et al. (1992).

In the tables that follow all timings are in CPU seconds and were obtained on an Intel Core i5–4670 CPU running at 3.40 GHz with 16 gigabytes of RAM. We used Maple 2017, Magma 2.22–5 and Singular 3–1–6. For all Maple timings, because Singular and Magma have only serial codes, we set `kernelopts(numcpus=1)`; to restrict Maple to use only one core as otherwise it will do polynomial multiplications and divisions in parallel.

8.1. Factoring determinants of Toeplitz and Cyclic matrices

Let C_n denote the $n \times n$ cyclic matrix and let T_n denote the $n \times n$ symmetric Toeplitz. See Fig. 2. The data in Tables 6 and 7 are for factoring the determinants of C_n and T_n . The polynomials $\det T_n$

$$C_n = \begin{pmatrix} x_1 & x_2 & \dots & x_{n-1} & x_n \\ x_n & x_1 & \dots & x_{n-2} & x_{n-1} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ x_3 & x_4 & \dots & x_1 & x_2 \\ x_2 & x_3 & \dots & x_n & x_1 \end{pmatrix} \quad \text{and} \quad T_n = \begin{pmatrix} x_1 & x_2 & \dots & x_{n-1} & x_n \\ x_2 & x_1 & \dots & x_{n-2} & x_{n-1} \\ & & \ddots & & \\ x_{n-1} & x_{n-2} & \dots & x_1 & x_2 \\ x_n & x_{n-1} & \dots & x_2 & x_1 \end{pmatrix}$$

Fig. 2. The determinants of C_n and T_n are homogeneous polynomials in x_1, x_2, \dots, x_n .

and $\det C_n$ are homogeneous. For homogeneous polynomials, Maple, Magma, Singular all first de-homogenize the polynomial to be factored. After factoring the de-homogenized polynomial, they homogenize the factors to obtain the actual factors.

To have a fair comparison, we de-homogenized the determinants by fixing $x_n = 1$ for all three systems. That is, for the determinant $\det T_n$ (or $\det C_n$), we time the factorization of $d_n = \det T_n(x_n = 1)$. In this way, we eliminate the de-homogenization and homogenization time which can be significant, as the determinants and the factors to be computed are huge for large n . Also d_n is monic in x_1 , so we eliminate the leading coefficient correction timing for MTSHL. Finally by any choice of ideal, the univariate factorization time of the projection of d_n into $\mathbb{Z}[x_1]$ is negligible, that is, the timings simply represent multivariate Hensel lifting time for all three systems.

The column MDP shows the number of calls (including recursive calls) to Maple’s MDP algorithm and the percentage of time in Hensel lifting spent solving MDPs. Data for the number of terms of $\det T_n$ and $\det C_n$ and the number of terms of their factors is also given in Tables 6 and 7. In Table 7 notice that the second factor for $n = 7, 11, 13$ has more terms than $\det C_n$. Also in Table 7 NA means we could neither compute the determinant in Singular using Singular’s determinant command nor read the determinant nor its factors into Singular to time Singular’s factorize command.

The data confirms the data from Monagan and Pearce (2014) that Maple’s multivariate factorization code is relatively fast. This is mainly because the underlying polynomial arithmetic is fast (Monagan and Pearce, 2014). We note here that Maple, Magma (see Steel, 2015) and Singular (see Lee, 2013) are all doing Hensel lifting one variable at a time (see Algorithm 6.4 of Geddes et al. (1992)) and lifting solutions to MDP equations one variable at a time (see Algorithm 6.2 of Geddes et al., 1992). All coefficient arithmetic is done modulo a prime p or prime power p^l which bounds the size the coefficients of any factors of the input. Singular (see Lee, 2013) differs from Maple and Magma in that it first factors a bivariate image $f(x_1, x_2, \alpha_3, \dots, \alpha_n)$ over \mathbb{Z} then starts the Hensel lifting from bivariate images of the factors.

8.2. Factoring Toeplitz and Cyclic matrices with MTSHL

For MTSHL, it is important that α_i ’s in the ideal $I = \langle x_2 - \alpha_1, x_3 - \alpha_2, \dots, x_n - \alpha_{n-1} \rangle$ are chosen from a large interval. For these we chose α_i ’s randomly from $[1, 65520]$. On the other hand, note that when we factored d_n with Maple, Magma and Singular to form Tables 6 and 7, Wang’s algorithm chose its own ideal. It can include some zeros, although it is not possible to choose all zero for these examples.

Tables 8 and 9 present timings for Hensel lifting to factor d_n , the de-homogenized $\det T_n$ and $\det C_n$ with MTSHL. The column notation used in the tables is explained in Fig. 3.

Table 6

Factorization timings in CPU seconds for factoring $d_n = \det(T_n)(x_n = 1)$, the determinant of the n by n Toeplitz matrix T_n evaluated at $x_n = 1$. NA = Not Attempted.

n	$\#d_n$	#factors	Maple	MDP		Magma	Singular
7	427	30,56	0.035	161	30%	0.01	0.02
8	1628	167,167	0.065	383	43%	0.04	0.05
9	6090	153,294	0.166	1034	73%	0.10	0.28
10	23797	931,931	0.610	2338	76%	0.89	1.77
11	90296	849,1730	2.570	6508	74%	1.96	8.01
12	350726	5579,5579	19.45	15902	80%	72.17	84.04
13	1338076	4983,10611	84.08	45094	84%	181.0	607.99
14	5165957	34937,34937	637.8	103591	77%	6039.0	20333.45
15	19732508	30458,66684	4153.2	286979	84%	12899.2	NA

Table 7

Factorization data and timings in CPU seconds for factoring $d_n = \det(C_n)(x_n = 1)$, the determinant of the n by n Cyclic matrix C_n evaluated at $x_n = 1$. NA = Not Attempted.

n	$\#d_n$	#factors	Maple	MDP		Magma	Singular
7	246	7,924	0.045	330	90%	0.01	0.02
8	810	8,8,20,86	0.059	218	46%	0.07	0.06
9	2704	9,45,1005	0.225	1810	74%	0.74	0.24
10	7492	10,10,715,715	0.853	1284	62%	8.44	2.02
11	32066	11,184756	7.160	75582	91%	104.3	11.39
12	86500	12,12,42,78,78,621	19.76	1884	76%	7575.1	30.27
13	400024	13, 2704156	263.4	1790701	92%	30871.90	NA
14	1366500	14,14,27132,27132	1664.4	50381	77%	$> 10^6$	288463.17
15	4614524	15,120,3060,303645	18432.	477882	82%	NA	NA

Table 8

Timings for factoring $\det(T_n)(x_n = 1)$.

n	t_{f_1}	t_{f_2}	tWang	tMTSHL	t_{mul}	t_{eval}
7	0.27	0.36	0.035 (0.015)	0.046 (0.037)	0.001	0.003
8	0.50	0.50	0.065 (0.028)	0.073 (0.059)	0.007	0.005
9	0.31	0.23	0.166 (0.121)	0.122 (0.075)	0.018	0.001
10	0.47	0.47	0.610 (0.467)	0.418 (0.251)	0.099	0.024
11	0.22	0.28	2.570 (1.902)	1.138 (0.458)	0.339	0.053
12	0.45	0.45	19.45 (15.56)	13.165 (5.445)	3.779	0.897
13	0.27	0.21	84.08 (70.623)	21.769 (11.064)	6.904	4.361
14	0.45	0.45	637.8 (491.106)	249.961 (160.04)	71.351	102.918
15	0.21	0.26	4153.2 (1771.54)	1651.68 (689.634)	674.356	405.016

Table 9

Timings for factoring $\det(C_n)(x_n = 1)$.

n	tWang	tMTSHL	t_{mul}	t_{eval}
7	0.041 (0.012)	0.026 (0.015)	0.002	0.001
8	0.057 (0.025)	0.063 (0.046)	0.010	0.003
9	0.209 (0.152)	0.12 (0.042)	0.024	0.002
10	0.845 (0.642)	0.5 (0.22)	0.20	0.01
11	6.6 (4.884)	0.945 (0.094)	0.386	0.003
12	19.76 (15.808)	5.121 (1.385)	3.108	0.048
13	252.2 (211.848)	27.689 (1.474)	9.362	0.093
14	1861.8 (1563.912)	523.073 (85.326)	346.067	38.399
15	18432.0 (14929.2)	7496.94 (426.014)	3602.739	19.231

tWang	is the time for Wang’s algorithm which Maple currently uses (see Geddes et al., 1992),
tBS	is the time for the factoring algorithm based on Algorithm 3; it uses Zippel’s variable at a time sparse interpolation,
tMTSHL	is the time where factoring algorithm is based on Algorithm 5,
tX(tY)	means factoring time tX with tY seconds spent on solving MDP,
t_{mul}	means time spent on multiplication in MTSHL,
t_{eval}	means time spent on evaluation in MTSHL,
T_{f_i}	denotes the number of terms of a factor,
t_{f_i}	denotes the density ratio of a factor

Fig. 3. Notation for Tables 8–12.

The density ratio of factors of d_n can be seen in Table 8. For example, the de-homogenization of d_n is of total degree 15 which has 2 factors. The first factor computed is in 14 variables of total degree 8, has 66684 terms and density ratio 0.208537. The second factor is in 14 variables of total degree 7, has 30458 terms and density ratio 0.261937.

Factoring d_n is a challenging problem. They are huge and can be considered as dense polynomials. The factors have total degree less than their total number of variables. Our natural expectation in this case is that Wang’s approach is preferable to sparse approaches.

As can be seen from Table 6, if we factor d_{14} and d_{15} using Maple that uses Wang’s algorithm for multivariate factorization, the calculation will take 637 s and 4153 s resp. MTSHL factors d_{14} and d_{15} in 250 s and 1650 s resp.

Table 9 presents timings for Hensel lifting to factor $d_n = \det C_n$ with MTSHL. **For C_n the density ratio is 1** for all factors except for $n = 12$, in which out of 6 factors one has $t_f = 0.53$ and one has $t_f = 0.45$ and for $n = 15$, one of the 4 factors has density ratio 0.95.

The timings in the columns tWang and tMTSHL show that in general the most time dominating step of MHL is solving MDP and it confirms that even for complicated examples MTSHL is quicker than Wang’s algorithm, because it spends less time to solve MDP. Also, the values in the columns t_{mul} and t_{eval} confirm the theoretical complexity analysis that evaluation and multiplication are the most time dominating operations in MTSHL. We have not reported the time spent solving Vandermonde systems because it was always < 10%. Also, except for C_{15} the time spent in trial divisions is < 10%. For C_{15} it was 3362 seconds.

8.3. Factoring random sparse polynomials with MTSHL

To compare MTSHL with Wang’s algorithm on randomly generated examples, we created random sparse multivariate polynomials A, B in Maple and computed $C = AB$. We used $p = 2^{31} - 1$ and **two ideal types to factor C**:

- ideal type 1: $I = \langle x_2 - 0, x_3 - 0, \dots, x_n - 0 \rangle$ and
- ideal type 2: $I = \langle x_2 - \alpha_1, x_3 - \alpha_2, \dots, x_n - \alpha_n \rangle$

For Wang’s algorithm, the first attempt should be to try an ideal of type 1, because a sparse polynomial remains sparse in this case and hence the number of MDPs to be solved significantly decreases. If it does not work, for ideal type 2, the α_i ’s are chosen from a small interval including zero.

As noted it is not always possible to use ideal type 1 because the leading coefficient of C must not vanish at $\alpha_2, \dots, \alpha_n$ and also, the factors A and B must be relatively prime at $\alpha_2, \dots, \alpha_n$. To generate random examples where ideal type 1 cannot be used, we chose A and B of the form

- (i) $x_1^d + \left(\prod_{i=1}^n x_i\right) \cdot \text{randpoly}([x_1, \dots, x_n], \text{degree} = d - n, \text{terms} = T, \text{coeffs} = \text{rand}(1..99))$
- (ii) $c + \sum_{i=1}^n x_i \cdot \text{randpoly}([x_1, \dots, x_n], \text{degree} = d - 1, \text{terms} = T/n, \text{coeffs} = \text{rand}(1..99))$

Table 10

The timing table for random data with ideal type 2, (i).

$n/d/T$	tWang	tMTSHL	$n/d/T$	tWang	tMTSHL
3/35/100	1.85 (1.34)	0.72 (0.04)	7/35/100	567.97 (566.61)	2.27 (0.53)
3/35/500	3.36 (1.80)	1.70 (0.06)	7/35/500	> 3000. stopped	43.14 (6.84)
5/35/100	50.90 (49.59)	2.10 (0.31)	8/35/100	1859.86 (1858.20)	2.31 (0.55)
5/35/500	237.84 (217.31)	32.12 (2.88)	8/35/500	> 3000. stopped	47.45 (7.39)
6/35/100	174.22 (174.21)	2.03 (0.42)	9/35/100	> 3000. stopped	2.94 (0.56)
6/35/500	923.00 (897.28)	39.00 (5.10)	9/35/500	> 3000. stopped	79.59 (9.72)

Table 11

The timing table for random data with ideal type 2, (ii).

$n/d/T$	tWang	tMTSHL	$n/d/T$	tWang	tMTSHL
3/20/100	0.264 (0.204)	0.15 (0.007)	7/20/100	30.442 (29.654)	0.958 (0.29)
3/20/500	0.443 (0.247)	0.288 (0.01)	7/20/500	138.128 (129.054)	14.285 (3.081)
5/20/100	4.131 (3.682)	0.581 (0.126)	9/20/100	113.421 (112.632)	1.09 (0.359)
5/20/500	21.922 (17.635)	5.028 (1.009)	9/20/500	1088.882 (1073.387)	20.528 (5.6)

Table 12

The timing table for random data with ideal type 1.

$n/d/T$	t_f	tWang	tBS
5/20/5000	0.1	7.08 (2.605)	11.804 (7.376)
5/15/3000	0.2	4.25 (1.554)	4.963 (2.29)
5/15/5000	0.3	6.882 (2.988)	6.471 (2.99)
4/20/5000	0.4	2.709 (1.211)	2.704 (1.267)
5/20/30000	0.56	86.224 (18.394)	90.111 (21.134)

where c is small positive integer and the Maple command `randpoly` again is used to generate random polynomials. So, for (i), one must choose all non-zero evaluation points and for (ii) one cannot choose ideal type 1 but one can choose some zero evaluation points for Wang’s algorithm.

Tables 10 and 11 present timings for the randomly generated data of the form (i) and (ii). They show that for the both cases MTSHL is significantly faster than Wang’s algorithm.

We also included timings for ideal type 1 case, as according to our experiments, it is the only case where Wang’s algorithm is quicker. In this case, the evaluation cost of sparse interpolation becomes dominant which is not the case for Wang’s algorithm. To generate random examples where ideal type 1 can be used, we chose A and B in the form

$$x_1^d + \text{randpoly}([x_1, \dots, x_n], \text{degree} = d - 1, \text{terms} = T) + c$$

where c is a small positive integer.

Table 12 presents timings for the random data for which ideal type 1 is used. For the ideal type 1 case MTSHL was not used, since the zero evaluation probability is large for the sparse case. According to our experiments Wang’s algorithm is faster for $t_f < 0.2$. For $t_f \geq 0.2$ the performance of Wang’s algorithm and Algorithm 3 (which uses sparse interpolation without the strong SHL assumption) are almost the same.

9. Notes for the multi-factor case

We have only presented algorithms for the case when $a(x_1, \dots, x_n)$ has two irreducible factors f and g . Let $a_{j-1} = f_1 f_2 \dots f_m$ with $m \geq 2$ be the factorization of a_j from step $j - 1$ with $f_i \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$. At the j th step of Hensel lifting, Algorithm 5 must solve multivariate polynomial diophantine equations of the form

$$\sigma_1 \frac{a_{j-1}}{f_1} + \sigma_2 \frac{a_{j-1}}{f_2} + \dots + \sigma_m \frac{a_{j-1}}{f_m} = c_i$$

for $\sigma_i \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$ with $\deg(\sigma_i, x_1) < \deg(f_i, x_1)$ for $1 \leq i \leq m$. An algorithm for solving this m term MDP is given in Ch. 6 of Geddes et al. (1992). It first solves $\sigma_1 \frac{a_{j-1}}{f_1} + \tau_1 f_1 = c_i$ for σ_1 and τ_1 where $\tau_1 = \sum_{i=2}^m \sigma_i \frac{a_j}{f_1 f_i}$. Then it solves $\sum_{i=2}^m \sigma_i \frac{a_j}{f_1 f_i} = \tau_1$ for the σ_i recursively. Thus it solves $m - 1$ two term MDPs. In Monagan and Tuncer (2018) we experimented with using sparse interpolation to simultaneously interpolate all σ_i from bivariate images and found that this lead to a speedup of typically a factor of $m - 1$.

10. Conclusion

We have shown that solving the multivariate polynomial diophantine equations that arise in Wang’s multivariate Hensel lifting algorithm can be improved by using sparse interpolation. Whereas Wang’s method (see Algorithm 2) can be exponential in the number of variables our new algorithm MTSHL is polynomial in the size of the input polynomial and its factors. Our experiments show that MTSHL is faster than Wang’s method in practice. The second author has integrated MTSHL into Maple’s factorization code under a MITACS internship with Dr. Jürgen Gerhard of Maplesoft. The new code became the default factorization algorithm used by Maple’s `factor` command for multivariate polynomials with integer coefficients in Maple 2019. The old code, which uses Wang’s algorithm, is still accessible as an option.

In the paper we have attempted an average case complexity analysis for our algorithm. In order to do this we needed to know how many terms appear in a sparse polynomial $f(x_1, \dots, x_n)$ when we successively evaluate its variables at integers one at a time. We also needed to know how many terms appear in the coefficients of a Taylor expansion of a sparse polynomial expanded about a non-zero point. These results (Lemma 10 and Lemma 18) may be useful elsewhere.

Maple code for generating the data presented in Tables 1, 2, 3, 4 and 5 is available on the web under <http://www.cecm.sfu.ca/CAG/code/MTSHL> as a Maple worksheet `PaperExamples.mw`, a `.pdf` file `PaperExamples.pdf` and also as a Maple `.mpl` file `PaperExamples.mpl`.

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Acknowledgements

We thank Roman Pearce for his C code for polynomial evaluation for the method in Section 2.4 and Jürgen Gerhard for suggesting the S polynomial in the proof of Proposition 3. We also thank the anonymous referees for their many suggestions to improve this paper. We acknowledge the support of NSERC of Canada, RGPIN-2014-04238.

Appendix A. Example of Algorithm 5

We give an example of Algorithm 5 (MTSHL). Suppose we seek to factor $a = fg$ where

$$f = x_1^8 + 2x_1x_2^2x_4^3x_5 + 4x_1x_2^2x_3^3 + 3x_1x_2^2x_4x_5^2 + x_2^2x_3x_4 - 5$$

$$g = x_1^8 + 3x_1^2x_2x_3x_4^2x_5 + 5x_1^2x_2x_3^2x_4 - 3x_4^2x_5^2 + 4x_5$$

Let $\alpha_5 = 1$ and $p = 2^{31} - 1$. First we factor $a(x_5 = \alpha_5)$ recursively to obtain

$$f_0 := f(x_5 = 1) = x_1^8 + 4x_1x_2^2x_3^3 + 2x_1x_2^2x_4^3 + 3x_1x_2^2x_4 + x_2^2x_3x_4 - 5$$

$$g_0 := g(x_5 = 1) = x_1^8 + 5x_1^2x_2x_3^2x_4 + 3x_1^2x_2x_3x_4^2 - 3x_4^2 + 4$$

satisfying $a(x_5 = \alpha_5) = f_0g_0$. Now let $f = \sum_{i=0}^{\deg_{x_5} f} f_i(x_5 - 1)^i$ and $g = \sum_{i=0}^{\deg_{x_5} g} g_i(x_5 - 1)^i$. If the SHL assumption is true at the first step then f_1 and g_1 have the form

$$f_1 = (b_1x_3^3 + b_2x_4^3 + b_3x_4)x_1x_2^2 + b_4x_2^2x_3x_4 + b_5$$

$$g_1 = (b_6x_3^2x_4 + b_7x_3x_4^2)x_1^2x_2 + b_8x_4^2 + b_9$$

for unknowns $\{b_1, \dots, b_9\}$. In the following c_k denotes the coefficient of $(x_5 - 1)^k$ in the Taylor expansion of the error about $x_5 = 1$. Let also $f^{(0)} := f_0$, $g^{(0)} := g_0$, $f^{(k)} := \sum_{i=0}^k f_i(x_5 - 1)^i$ and $g^{(k)} := \sum_{i=0}^k g_i(x_5 - 1)^i$. We start by computing $c_1 = \text{coeff}(a - f^{(0)}g^{(0)}, x_5 - 1)$ the first Taylor coefficient of the error. We obtain

$$c_1 = 3x_1^{10}x_2x_3x_4^2 + 2x_1^9x_2^2x_4^3 + 6x_1^9x_2^2x_4 + 12x_1^3x_2^3x_3^4x_4^2 + 10x_1^3x_2^3x_3^2x_4^4$$

$$+ 12x_1^3x_2^3x_3x_4^5 - 6x_1^8x_4^2 + 30x_1^3x_2^3x_3^2x_4^2 + 27x_1^3x_2^3x_3x_4^3 + 3x_1^2x_2^3x_3^2x_4^3$$

$$+ 4x_1^8 - 24x_1x_2^2x_3^3x_4^2 - 18x_1x_2^2x_4^5 - 15x_1^2x_2x_3x_4^2 + 16x_1x_2^2x_3^3$$

$$- 20x_1x_2^2x_4^3 - 6x_2^2x_3x_4^3 + 36x_1x_2^2x_4 + 4x_2^2x_3x_4 + 30x_4^2 - 20$$

The MDP to be solved is $D := g_1f_0 + f_1g_0 = c_1$. Since f_1 has three terms in $x_1x_2^2$ and g_1 has two terms in $x_1^2x_2$ we will interpolate g_1 using two evaluations then obtain f_1 by division. We choose $(x_3 = 2, x_4 = 3)$ and $(x_3 = 2^2, x_4 = 3^2)$ and compute $D(x_3 = 2, x_4 = 3)$:

$$(x_1^8 + 95x_1x_2^2 + 6x_2^2 - 5) \left((12b_6 + 18b_7)x_1^2x_2 + 9b_8 + b_9 \right)$$

$$+ (x_1^8 + 114x_1^2x_2 - 23) \left((8b_1 + 27b_2 + 3b_3)x_1x_2^2 + 6b_4x_2^2 + b_5 \right)$$

$$= 54x_1^{10}x_2 + 72x_1^9x_2^2 - 50x_1^8 + 13338x_1^3x_2^3 + 324x_1^2x_2^3 - 270x_1^2x_2$$

$$- 6406x_1x_2^2 - 300x_2^2 + 250$$

and similarly $D(x_3 = 4, x_4 = 9)$. Calling BDP to solve these bivariate Diophantine equations we obtain the solutions $[\sigma_1, \tau_1] = [54x_1^2x_2 - 50, 72x_1x_2^2]$ and $[\sigma_2, \tau_2] = [972x_1^2x_2 - 482, 1512x_1x_2^2]$. Hence we have

$$(12b_6 + 18b_7)x_1^2x_2 + 9b_8 + b_9 = 54x_1^2x_2 - 50$$

$$(144b_6 + 324b_7)x_1^2x_2 + 81b_8 + b_9 = 972x_1^2x_2 - 482$$

Then we solve the Vandermonde linear systems

$$\begin{bmatrix} 12 & 18 \\ 144 & 324 \end{bmatrix} \begin{bmatrix} b_6 \\ b_7 \end{bmatrix} = \begin{bmatrix} 54 \\ 972 \end{bmatrix} \text{ and } \begin{bmatrix} 9 & 1 \\ 81 & 1 \end{bmatrix} \begin{bmatrix} b_8 \\ b_9 \end{bmatrix} = \begin{bmatrix} -50 \\ -482 \end{bmatrix}$$

to obtain $b_6 = 0, b_7 = 3, b_8 = -6, b_9 = 4$. So $g_1 = 3x_1^2x_2x_3x_4^2 - 6x_4^2 + 4$. Then by division we get $f_1 = (c_1 - f_0g_1)/g_0 = 2x_1x_2^2x_4^3 + 6x_1x_2^2x_4$. Hence

$$f^{(1)} = f_0 + (2x_1x_2^2x_4^3 + 6x_1x_2^2x_4)(x_5 - 1)$$

$$g^{(1)} = g_0 + (3x_1^2x_2x_3x_4^2 - 6x_4^2 + 4)(x_5 - 1).$$

Note that we use the division step above also as a check for the correctness of the SHL assumption that $\text{Supp}(g_1) \subseteq \text{Supp}(g_0)$. Since the solution to the MDP is unique, we would have g_0 does not divide $(c_1 - f_0g_1)$, if this assumption were wrong.

Now following Lemma 1 by looking at the monomials of f_1 and g_1 , we assume that the forms of the f_2 and g_2 are

$$f_2 = b_1x_1x_2^2x_4^3 + b_2x_1x_2^2x_4 + b_3$$

$$g_2 = b_4x_1^2x_2x_3x_4^2 + b_5x_4^2 + b_6$$

for some unknowns $\{b_1, \dots, b_6\}$. After computing the next error $a - f^{(1)}g^{(1)}$ we compute c_2 and the MDP to be solved is $D := f_0g_2 + g_0f_2 = c_2$. We need 2 evaluations again to solve for g_2 . Choose $(x_3 = 5, x_4 = 6)$ and $(x_3 = 5^2, x_4 = 6^2)$ and compute

$$\begin{aligned} D(x_3 = 5, x_4 = 6) &:= \left(x_1^8 + 950x_1x_2^2 + 30x_2^2 - 5\right) \left(180b_4x_1^2x_2 + 36b_5 + b_6\right) \\ &\quad + \left(x_1^8 + 1290x_1^2x_2 - 104\right) \left(216b_1x_1x_2^2 + 6b_2x_1x_2^2 + b_3\right) \\ &= 18x_1^9x_2^2 - 108x_1^8 + 23220x_1^3x_2^3 - 104472x_1x_2^2 - 3240x_2^2 + 540 \end{aligned}$$

and similarly for $D(x_3 = 25, x_4 = 36)$. Calling BDP we obtain the solutions to these bivariate Diophantine equations $[\sigma_1, \tau_1] = [-108, 18x_1x_2^2]$ and $[\sigma_2, \tau_2] = [-3888, 108x_1x_2^2]$ respectively. Hence we have $180b_4x_1^2x_2 + 36b_5 + b_6 = -108$ and $32400b_4x_1^2x_2 + 1296b_5 + b_6 = -3888$ respectively. Then we solve the Vandermonde linear systems

$$[180][b_4] = [0] \text{ and } \begin{bmatrix} 36 & 1 \\ 1296 & 1 \end{bmatrix} \begin{bmatrix} b_5 \\ b_6 \end{bmatrix} = \begin{bmatrix} -108 \\ -3888 \end{bmatrix}$$

to obtain $b_4 = 0, b_5 = -3, b_6 = 0$. So $g_2 = -3x_4^2$. Then by division we get $f_2 = (c_2 - f_0g_2)/g_0 = 3x_1x_2^2x_4(x_5 - 1)^2$. Hence

$$\begin{aligned} f^{(2)} &= f^{(1)} + 3x_1x_2^2x_4(x_5 - 1)^2 \\ &= x_1^8 + 2x_1x_2^2x_4^3x_5 + 4x_1x_2^2x_3^3 + 3x_1x_2^2x_4x_5^2 + x_2^2x_3x_4 - 5 \\ g^{(2)} &= g^{(1)} + (-3x_4^2)(x_5 - 1)^2 \\ &= x_1^8 + 3x_1^2x_2x_3x_4^2x_5 + 5x_1^2x_2x_3^2x_4 - 3x_4^2x_5^2 + 4x_5. \end{aligned}$$

Since the next error $a - f^{(2)}g^{(2)} = 0$ we have found the factors of a .

Appendix B. Algorithm BDP

Algorithm 4 SparseInterpolate in Section 2.3 must solve many bivariate polynomial diophantine problems in Step 8. These are equations of the form $\sigma A + \tau B = C$ where A, B, C are given polynomials in $\mathbb{Z}_p[x_1, x_2]$. If $\gcd(A, B) = 1$ then solutions for σ and τ exist and in general they are in the fraction field $\mathbb{Z}_p(x_2)[x_1]$. In Algorithm 4 we are looking for polynomial solutions in $\mathbb{Z}_p[x_1, x_2]$. Moreover, because the polynomials A, B and C come from evaluating u, v and c in Step 8 of Algorithm 4, even though $\gcd(u, v) = 1$ in $\mathbb{Z}_p[x_1, x_2, \dots, x_{j-1}]$, it may be that $\gcd(A, B) \neq 1$ in $\mathbb{Z}_p[x_1, x_2]$.

We present Algorithm 6 (BDP) which is a modular algorithm. It picks evaluation points $\gamma_k \in \mathbb{Z}_p$, solves univariate diophantine equations

$$\sigma_k A(x_1, \gamma_k) + \tau_k B(x_1, \gamma_k) = C(x_1, \gamma_k)$$

in $\mathbb{Z}_p[x_1]$ and interpolates x_2 in σ and τ from these images. In many respects Algorithm 6 is similar to the modular GCD Algorithm for computing a gcd in $\mathbb{Z}_p[x_1, x_2]$. See Algorithm 6.36 of von zur Gathen and Gerhard (2013) and Algorithm 7.2 of Geddes et al. (1992).

We first discuss what the input D_2 should be. Recall that at the j th step of Hensel lifting (Algorithms 1 and 5) we have inputs a_j, f_{j-1}, g_{j-1} and we compute

$$f_j = f_{j-1} + \sum_{i=1}^j \sigma_i(x_j - \alpha_j)^i \text{ and } g_j = g_{j-1} + \sum_{i=1}^j \tau_i(x_j - \alpha_j)^i$$

such that $a_j = f_j g_j$. In Step 6 of Algorithm 1 and Step 9 of Algorithm 5, we solve the MDP $\sigma_i f_{j-1} + \tau_i g_{j-1} = c_i$ for $\sigma_i, \tau_i \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$. Since σ, τ, A, B, C in Algorithm 6 are bivariate images of

Algorithm 6 Bivariate Diophantine Problem (BDP) solver.

Input: Polynomials $A, B, C \in \mathbb{Z}_p[x_1, x_2]$ satisfying A, B are monic in x_1 and $\deg(A, x_1) + \deg(B, x_1) < \deg(C, x_1)$, and a degree bound D_2 .

Output: Polynomials $\sigma, \tau \in \mathbb{Z}_p[x, y]$ satisfying (i) $\sigma A + \tau B = C$ in $\mathbb{Z}_p[x_1, x_2]$, (ii) $\deg(\sigma, x_1) < \deg(B, x_1)$ and $\deg(\tau, x_1) < \deg(A, x_1)$ and (iii) $\deg(\sigma A, x_2) \leq D_2$ and $\deg(\tau B, x_2) \leq D_2$, or, BDP outputs FAIL meaning no such polynomials exist or BDP was unlucky.

```

1: for  $k = 0$  to  $D_2$  do
2:   Pick a new evaluation point  $\gamma_k$  from  $\mathbb{Z}_p$  at random.
3:    $(A_k, B_k, C_k) \leftarrow (A(x_1, \gamma_k), B(x_1, \gamma_k), C(x_1, \gamma_k))$ 
4:   Solve  $SA_k + TB_k = \gcd(A_k, B_k)$  for  $S, T \in \mathbb{Z}_p[x_1]$  using the EEA.
5:   if  $\gcd(A_k, B_k) \neq 1$  return FAIL endif.
6:   // Solve  $\sigma B_k + \tau A_k = C_k$  for  $\sigma_k, \tau_k \in \mathbb{Z}_p[x_1]$ :
7:    $\sigma_k \leftarrow (C_k \times S) \bmod B_k$ .
8:    $\tau_k \leftarrow (C_k - \sigma_k A_k) \text{ quo } B_k$ .
9: end for
10: Find  $\sigma(x_1, x_2)$  such that  $\sigma(x_1, \gamma_k) = \sigma_k$  for  $0 \leq k \leq D_2$  // Interpolate  $x_2$  in  $\sigma$ 
11: Find  $\tau(x_1, x_2)$  such that  $\tau(x_1, \gamma_k) = \tau_k$  for  $0 \leq k \leq D_2$  // Interpolate  $x_2$  in  $\tau$ 
12: if  $\deg(\sigma, x_2) + \deg(A, x_2) > D_2$  or  $\deg(\tau, x_2) + \deg(B, x_2) > D_2$  then
13:   return FAIL
14: else
15:   return  $(\sigma, \tau)$ 
16: end if

```

$\sigma_i, \tau_i, g_{j-1}, f_{j-1}$ and c_i respectively, we have $\deg(\sigma, x_2) \leq \deg(\sigma_i)$ and $\deg(\tau, x_2) \leq \deg(\tau_i, x_2)$. Since we seek f_j and g_j such that $a_j = f_j g_j$ we have

$$\deg(\sigma_j g_j, x_2) \leq \deg(a_j, x_2) \text{ and } \deg(\tau_j f_j, x_2) \leq \deg(a_j, x_2)$$

thus $D_2 = \deg(a, x_2)$ is what we should use for D_2 in Algorithm 6 to interpolate σ_j and τ_j in Algorithms 3 and 4.

If $\gcd(A, B) \neq 1$, Algorithm 6 immediately, when $k = 0$, outputs FAIL in Step 5. In what follows we will assume $\gcd(A, B) = 1$ which is the expected case.

By Th. 2.6 of Geddes et al. (1992) the solutions σ_k, τ_k computed in Steps 7 and 8 satisfy $\deg(\sigma_k, x_1) < \deg(B_k, x_1)$ and $\deg(\tau_k, x_1) < \deg(A_k, x_1)$. It follows that after interpolation of x_2 condition (ii) will be satisfied. Condition (iii) is imposed by the termination test in Step 12. It remains to prove that condition (i) holds at Step 15.

Let $M = \prod_{k=0}^{D_2} (x_2 - \gamma_k)$. After Step 8 we have $\sigma_k A_k + \tau_k B_k = C_k$. Thus after Steps 10 and 11 we have $\sigma(x_1, \gamma_k)A(x_1, \gamma_k) + \tau(x_1, \gamma_k)B(x_1, \gamma_k) = C(x_1, \gamma_k)$, that is, $(x_2 - \gamma_k)|(C - \sigma A + \tau B)$ in $\mathbb{Z}_p[x_1, x_2]$. Since this holds for all $0 \leq k \leq D_2$ and the γ_k are distinct we have $M|(C - \sigma A + \tau B)$ in $\mathbb{Z}_p[x_1, x_2]$. But $\deg(M, x_2) = D_2 + 1$ and the degree constraints on C, σ and τ mean $\deg(C - \sigma A - \tau B, x_2) \leq D_2$ thus $C - \sigma A - \tau B = 0$ and (i) is satisfied.

Assuming D_1 and D_2 bound the degrees of A, B, C, σ and τ in x_1 and x_2 , respectively, we claim that Algorithm 6 does $O(D_1^2 D_2 + D_1 D_2^2)$ arithmetic operations in \mathbb{Z}_p using classical algorithms for polynomial arithmetic. To see this the polynomial evaluations in Step 2 are $O(D_1 D_2)$, the extended Euclidean algorithm in Step 4 costs $O(D_1^2)$ (see Theorem 4.16 of von zur Gathen and Gerhard, 2013), and the polynomial multiplications and divisions in $\mathbb{Z}_p[x_1]$ in Steps 7 and 8 cost $O(D_1^2)$. Steps 10 and 11 perform at most D_1 interpolations in $\mathbb{Z}_p[x_2]$, each of which is $O(D_2^2)$ (see Theorem 5.1 of von zur Gathen and Gerhard, 2013). Summing up, the total number of arithmetic operations in \mathbb{Z}_p Algorithm 6 does is $(D_2 + 1)[O(D_1 D_2) + O(D_1^2)] + O(D_1)O(D_2^2) = O(D_1^2 D_2 + D_1 D_2^2)$.

It remains to discuss the failure probability of Algorithm 6 in Step 4. We say γ_k is unlucky if $\gcd(A(x_1, \gamma_k), B(x_1, \gamma_k)) \neq 1$. Algorithm 6 needs $D_2 + 1$ lucky evaluation points to interpolate x_2 . Let

$R(x_2) = \text{res}(A, B, x_1)$ be the Sylvester resultant of A and B taken in x_1 . Since A and B are monic in x_1 we have

$$\text{gcd}(A(x_1, \gamma_k), B(x_1, \gamma_k)) \neq 1 \iff \text{res}(A(x_1, \gamma_k), B(x_1, \gamma_k), x_1) = 0 \iff R(\gamma_k) = 0.$$

Using the Schwartz-Zippel Lemma and Bezout’s Theorem, we have

$$\text{Prob}[R(\gamma_k) = 0] \leq \frac{\text{deg } R}{p} \leq \frac{\text{deg } A \text{ deg } B}{p}.$$

Thus for any $X \geq 2$, if $p > X(D_2 + 1) \text{deg } A \text{ deg } B + (D_2 + 1)$ then the probability that Algorithm 6 outputs FAIL in Step 4 is at most $1/X$. Note the extra term $(D_2 + 1)$ is needed since the γ_k are distinct. Thus, for the case $\text{gcd}(A, B) = 1$, Algorithm 6 is a Monte Carlo Algorithm with failure probability $\leq 1/X$.

Appendix C. Proof of Proposition 13

Proposition 13. Let $\mathcal{I} = \{i \in \mathbb{N} \mid t_f \leq 1/\binom{i+d}{d} \text{ and } i \leq n\}$. Then with probability $\geq 1 - \frac{dT_f}{2(p-1)}$, one has

- (i) $\frac{E[T_{f_i}]}{T_f} \geq 1 - t_f^2$ for $i \in \mathcal{I}$,
- (ii) if $n \leq d$, then $|\mathcal{I}| \geq \max\{1, \lceil n - \log_r T_f \rceil\}$ where $r = 1 + \frac{d}{n}$.

Proof. With probability $\geq 1 - \frac{dT_f}{2(p-1)}$, one has

$$E[T_{f_i}] = \sum_{k=0}^d s_k^{(i)} \left(1 - \frac{\binom{s-d_k^{(i)}}{s}}{\binom{s}{T_f}}\right)$$

where $d_k^{(i)} = \binom{d-k+i}{i}$. Note that

$$t_f \leq \frac{1}{\binom{i+d}{d}} \leq \frac{1}{d_k^{(i)}} \implies t_f d_k^{(i)} \leq 1. \tag{18}$$

It follows that

$$\frac{d_k^{(i)}}{s} = \frac{d_k^{(i)} t_f}{T_f} \leq \frac{1}{T_f}. \tag{19}$$

We have

$$\frac{\binom{s-d_k^{(i)}}{s}}{\binom{s}{T_f}} \leq (1 - t_f)^{d_k^{(i)}}. \tag{20}$$

Then

$$\begin{aligned} E[T_{f_i}] &= \sum_{k=0}^d s_k^{(i)} \left(1 - \frac{\binom{s-d_k^{(i)}}{s}}{\binom{s}{T_f}}\right) \stackrel{\text{by (20)}}{\geq} \sum_{k=0}^d s_k^{(i)} (1 - (1 - t_f)^{d_k^{(i)}}) \\ &= \sum_{k=0}^d s_k^{(i)} \left(1 - \sum_{j=0}^{d_k^{(i)}} (-1)^j \binom{d_k^{(i)}}{j} t_f^j\right) \end{aligned}$$

$$\begin{aligned}
 &= \sum_{k=0}^d s_k^{(i)} \left(1 - 1 + d_k^{(i)} t_f - \sum_{j=2}^{d_k^{(i)}} (-1)^j \binom{d_k^{(i)}}{j} t_f^j \right) \\
 &= t_f s - t_f^2 \sum_{k=0}^d \sum_{j=2}^{d_k^{(i)}} (-1)^j s_k^{(i)} \binom{d_k^{(i)}}{j} t_f^{j-2} \\
 &= T_f - t_f^2 \sum_{k=0}^d \sum_{j=2}^{d_k^{(i)}} (-1)^j s_k^{(i)} \binom{d_k^{(i)}}{j} t_f^{j-2}.
 \end{aligned}$$

The expected decrease in the number of terms is determined by the quantity

$$A = t_f^2 \sum_{k=0}^d \sum_{j=2}^{d_k^{(i)}} (-1)^j s_k^{(i)} \binom{d_k^{(i)}}{j} t_f^{j-2}.$$

We have

$$s_k^{(i)} \binom{d_k^{(i)}}{j} t_f^{j-2} < s_k^{(i)} \frac{\left(d_k^{(i)}\right)^j}{j!} t_f^{j-2} \stackrel{\text{by (18)}}{\leq} \frac{s_k^{(i)} \left(d_k^{(i)}\right)^2}{j!}.$$

Then the absolute value of A is

$$|A| \leq t_f^2 \sum_{k=0}^d \sum_{j=2}^{d_k^{(i)}} \frac{s_k^{(i)} \left(d_k^{(i)}\right)^2}{j!} = t_f^2 \sum_{k=0}^d s_k^{(i)} \left(d_k^{(i)}\right)^2 \underbrace{\sum_{j=2}^{d_k^{(i)}} \frac{1}{j!}}_{\leq 1} \leq t_f^2 \sum_{k=0}^d s_k^{(i)} \left(d_k^{(i)}\right)^2.$$

So we see that

$$\frac{|A|}{T_f} \leq \frac{t_f^2 \sum_{k=0}^d s_k^{(i)} \left(d_k^{(i)}\right)^2}{t_f s} = t_f \sum_{k=0}^d s_k^{(i)} d_k^{(i)} \frac{d_k^{(i)}}{s} \stackrel{\text{by (19)}}{\leq} t_f \frac{1}{T_f} s = t_f^2. \tag{21}$$

Then

$$\frac{E[T_{f,i}]}{T_f} \geq \frac{T_f - A}{T_f} \geq \frac{T_f - |A|}{T_f} = 1 - \frac{|A|}{T_f} \stackrel{\text{by (21)}}{\geq} 1 - t_f^2.$$

This proves the first part. For the second part, note that

$$t_f \leq \frac{1}{\binom{i+d}{d}} \iff T_f \leq \frac{\binom{n+d}{d}}{\binom{i+d}{d}} \iff \frac{1}{T_f} \geq \frac{\binom{i+d}{d}}{\binom{n+d}{d}}$$

and that $\frac{n-i}{n+d} = \frac{n}{n+d} - \frac{i}{n+d} = \frac{1}{1+d/n} - \frac{i}{n+d}$. So if $n \leq d$ then $\frac{n-i}{n+d}$ is small and the following bound is useful

$$\frac{\binom{i+d}{d}}{\binom{n+d}{d}} = \frac{\binom{n+d-(n-i)}{d}}{\binom{n+d}{d}} \leq \left(1 - \frac{d}{n+d}\right)^{n-i}.$$

Now if

$$T_f \leq \left(1 - \frac{d}{n+d}\right)^{i-n} \iff \frac{1}{T_f} \geq \left(1 - \frac{d}{n+d}\right)^{n-i} \implies i \in \mathcal{I}$$

and if we define $w = \frac{n}{n+d}$, then $w^n T_f \leq w^i \Rightarrow i \geq n + \log_w T_f$. Finally, if $r = \frac{1}{w} = 1 + \frac{d}{n}$, we have $i \geq n - \log_r T_f$. Hence if $n \leq d$, then $|\mathcal{I}| \geq \lceil n - \log_r T_f \rceil$. \square

Appendix D. The detailed analysis of MTSHL

Our aim in this appendix is first to estimate the complexity of this lifting process at the j th step of the MTSHL algorithm, that is, finding f_j and g_j , and then estimate the expected complexity of the multivariate factorization via MTSHL.

Recall that for $j \geq 3$, during the j th step of the Algorithm 5 (MTSHL), one aims to reach the factorization $a_j = f_j g_j \in \mathbb{Z}_p[x_1, \dots, x_j]$ from the knowledge of $a_j, f_{j-1}, g_{j-1} \in \mathbb{Z}_p[x_1, \dots, x_{j-1}]$ satisfying $a_{j-1} = f_{j-1} g_{j-1}$. Let $f_j = \sum_{i=0}^{d_j} f_{ji}(x_j - \alpha_j)^i, g_j = \sum_{i=0}^{d_j} g_{ji}(x_j - \alpha_j)^i$ for a randomly chosen non-zero element α_j in \mathbb{Z}_p and where $f_{j0} = f_{j-1}, g_{j0} = g_{j-1}$ and $\deg(a_j, x_j) = d_j$. For $1 \leq i \leq d_j$ one recovers each f_{ji}, g_{ji} by solving the MDP problems

$$f_{ji} g_{j0} + g_{ji} f_{j0} = c_{ji} \text{ in } \mathbb{Z}_p[x_1, \dots, x_{j-1}] \tag{22}$$

via sparse interpolation in a for loop where c_{ji} is the i th Taylor coefficient of *error*. Let also t_h, T_h denote the **expected** density ratio and the **expected** number of non-zero elements of a polynomial $h \in \mathbb{Z}_p[x_1, \dots, x_j]$.

Suppose that $T_{f_{j-1}} \leq T_{g_{j-1}}$. Then based on Lemma 10, MTSHL makes a probabilistic guess in Step 1 that T_{f_j} will be smaller than T_{g_j} and for $1 \leq i \leq d_j$, in the sparse interpolation routine, it first computes f_{ji} and then recovers g_{ji} via the multivariate division $(c_{ji} - g_{j0} f_{ji}) / f_{j0}$.

The cost of Step 4 is the cost of subtraction since we are given $a_{j-1} = f_{j-1} g_{j-1}$. In the sparse case, this cost is for sorting the monomials, which we will ignore for the rest of the discussion.

In the i th iteration, updating the monomial in Step 6 has cost linear in i which is negligible. Then, the algorithm computes the i th Taylor coefficient c_{ji} of the error at $x_j = \alpha_j$ in Step 7. Since this is linear in *#error* and thus dominated by the computation of the error in Step 4, it can be ignored.

Then to solve the MDP, it comes to the sparse interpolation in Step 11. Suppose that $f_{ji} = \sum c_{jik} x_1^k x_2^l \in \mathbb{Z}_p[x_3, \dots, x_{j-1}][x_1, x_2]$. Let $d_{ji} := d_j - i$ and $ev_{ji} := t_{f_{ji}} \binom{j-1-2+d_{ji}}{j-1-2}$. We have $\deg(f_{ji}) \leq d_{ji}$ and, as explained in Section 6, we expect that $\#c_{ji00} = ev_{ji}$. Then by Lemma 18, we expect

$$ev_{ji} := t_{f_{ji}} \binom{j-3+d_{ji}}{j-3} \leq t_{f_j} \frac{j+d_{ji}}{j} \binom{j-3+d_{ji}}{j-3}.$$

Based on the Lemma 1, Algorithm 5 makes a probabilistic guess in Step 10 and assumes that in sparse interpolation the solution form $\sigma_{f_{ji}} = f_{j,i-1}$, so the expected number of evaluations at the i th step is $\lceil ev_{j,i-1} \rceil$. According to Section 2.4 (see also Section 6), the expected cost $C_{Ev_{ji}}$ of evaluation at the i th step is bounded above by

$$C_{Ev_{ji}} < (T_{g_{j0}} + T_{f_{j0}} + T_{f_{j,i-1}} + T_{c_{ji}}) (\lceil ev_{j,i-1} \rceil + j - 4) + (j - 3) d_{j,i}$$

After evaluation, the sparse interpolation routine calls BDP. For a given bivariate diophantine equation the cost is $\mathcal{O}(d_{ji}^3)$. Hence the expected cost $C_{B_{ji}}$ of solving the bivariate diophantine equations via BDP in the i th iteration is

$$C_{B_{ji}} \in \mathcal{O}(\lceil ev_{j,i-1} \rceil d_{ji}^3).$$

Note again that the sparse interpolation routine first computes f_{ji} and then recovers g_{ji} via a multivariate division. The linear systems to be solved to recover f_{ji} corresponds to Vandermonde matrices and they are constructed by the unknown coefficients of the solution form $\sigma_{f_{ji}}$ of f_{ji} . Hence, if we define $r_{ji} = \frac{j-1}{j-1+d_{ji}}$, then the expected cost $C_{V_{ji}}$ of solving the linear system in the i th iteration is (see Section 6 equation (16))

$$C_{V_{ji}} \in \mathcal{O}(T_{f_{j,i-1}}^2 r_{j,i-1}^2).$$

By Lemma 18, $E[\#g_{j0}] \leq t_{g_j} \binom{j+d_j}{j}$ and $E[\#f_{ji}] \leq t_{f_j} \binom{j+d_{ji}}{j}$. So, after computing f_{ji} , the expected cost $C_{M_{ji}}$ of sparse multiplication $g_{j0}f_{ji}$ and the expected cost $C_{D_{ji}}$ of sparse division $(c_{ji} - g_{j0}f_{ji})/f_{j0}$ are both in

$$C_{M_{ji}} \text{ and } C_{D_{ji}} \in \mathcal{O} \left(t_{f_j} t_{g_j} \binom{j+d_j}{j} \binom{j+d_{ji}}{j} \right).$$

So far we have covered the (dominating) costs in sparse interpolation at the i th iteration. Next we consider (#14). The cost of updating, $C_{U_{ji}}$, i.e. computing $f_{ji}(x_j - \alpha_j)^i$ and $g_{ji}(x_j - \alpha_j)^i$ is in

$$C_{U_{ji}} \in \mathcal{O} \left(i(t_{f_j} + t_{g_j}) \binom{j+d_{ji}}{j} \right).$$

Finally, in Step 15, the cost of updating error is in (see the discussion at the end of Section 5)

$$C_{Er_{ji}} \in \mathcal{O} \left(\left(1 + \frac{d}{j}\right)^2 T_{f_j} T_{g_j} \right).$$

Let C_{Ev_j} be the expected total evaluation cost (in sparse interpolation) at the j th step. Then $C_{Ev_j} = \sum_{i=1}^{d_j} C_{Ev_{ji}}$. To compute it we'll split the sum

$$\sum_{i=1}^{d_j} (T_{g_{j0}} + T_{f_{j0}} + T_{f_{j,i-1}} + T_{c_{ji}}) (\lceil ev_{j,i-1} \rceil + j - 4) + (j - 3)d_{j,i-1}$$

and consider the parts separately: We first consider the sum

$$\begin{aligned} \sum_{i=1}^{d_j} \lceil ev_{j,i-1} \rceil &= \sum_{i=0}^{d_j-1} \lceil ev_{ji} \rceil \leq \sum_{i=0}^{d_j} \lceil t_{f_j} \frac{j+d_{ji}}{j} \binom{j-3+d_{ji}}{j-3} \rceil \\ &\leq \sum_{i=0}^{d_j} \left(t_{f_j} \frac{j+d_{ji}}{j} \binom{j-3+d_{ji}}{j-3} + 1 \right) = \sum_{i=0}^{d_j} t_{f_j} \frac{j+d_{ji}}{j} \binom{j-3+d_{ji}}{j-3} + \sum_{i=0}^{d_j} 1 \\ &\leq t_{f_j} \frac{j+d_j}{j} \sum_{i=0}^{d_j} \binom{j-3+d_{ji}}{j-3} + d_j = t_{f_j} \frac{j+d_j}{j} \binom{j-2+d_j}{j-2} + d_j \\ &= t_{f_j} \frac{j+d_j}{j} \frac{j-1}{j-1+d_j} \binom{j-1+d_j}{j-1} + d_j \leq t_{f_j} \binom{j-1+d_j}{j-1} + d_j \\ &= t_{f_j} \frac{j}{j+d_j} \binom{j+d_j}{j} + d_j = \frac{j}{j+d_j} T_{f_j} + d_j. \end{aligned}$$

As a next step, by recalling that f_{ji} is the i th Taylor coefficient of f_j , and we expect $T_{f_j} \leq T_{g_j}$, we get $T_{f_{j0}} \leq T_{f_j}$ and $T_{g_{j0}} \leq T_{g_j}$,

$$\sum_{i=1}^{d_j} (T_{g_{j0}} + T_{f_{j0}}) \lceil ev_{j,i-1} \rceil \leq (T_{f_j} + T_{g_j}) \left(\frac{j}{j+d_j} T_{f_j} + d_j \right) \in \mathcal{O} \left(\frac{j}{j+d_j} T_{f_j} T_{g_j} + d_j T_{g_j} \right). \tag{23}$$

On the other hand, we expect the size of the Taylor coefficients of the errors c_{ij} on the right hand of side of equation (22) satisfies $T_{c_{ji}} \leq T_{a_{j-1}} \leq T_{a_j}$. Then

$$\sum_{i=1}^{d_j} T_{c_{ji}} \lceil ev_{j,i-1} \rceil \leq T_{a_j} \sum_{i=1}^{d_j} \lceil ev_{j,i-1} \rceil \leq \frac{j}{j+d_j} T_{f_j} T_{a_j} + d_j T_{a_j}.$$

So, since we expect $T_{f_{j,i-1}} \leq T_{f_{j0}}$, we see that

$$\sum_{i=1}^{d_j} (T_{g_{j0}} + T_{f_{j0}} + T_{f_{j,i-1}} + T_{c_{ji}}) (\lceil ev_{j,i-1} \rceil) \in \mathcal{O}\left(\frac{j}{j+d_j} (T_{f_j} T_{g_j} + T_{f_j} T_{a_j}) + d_j (T_{g_j} + T_{a_j})\right). \tag{24}$$

Also,

$$\sum_{i=0}^{d_j-1} (j-3)d_{j,i} \in \mathcal{O}(jd_j^2). \tag{25}$$

Now we need to consider the sum

$$\sum_{i=1}^{d_j} T_{c_{ji}} j \leq \sum_{i=1}^{d_j} j t_{a_j} \binom{j+d_{ji}}{j} = j t_{a_j} \binom{j+d}{j+1} = j \frac{d_j}{j+1} T_{a_j} < d_j T_{a_j}.$$

Using the same idea we see that $\sum_{i=1}^{d_j} T_{f_{j,i-1}} j \leq d_j T_{f_j}$ and we have $\sum_{i=1}^{d_j} (T_{c_{ji}} + T_{f_{j,i-1}}) j \leq d_j (T_{f_j} + T_{a_j})$. Also,

$$\sum_{i=1}^{d_j} (T_{g_{j0}} + T_{f_{j0}}) j \leq (T_{f_j} + T_{g_j}) \sum_{i=1}^{d_j} j \leq (T_{f_j} + T_{g_j}) j d_j.$$

So we get

$$\sum_{i=1}^{d_j-1} (T_{g_{j0}} + T_{f_{j0}} + T_{f_{j,i-1}} + T_{c_{ji}}) j \in \mathcal{O}\left(jd_j (T_{f_j} + T_{g_j}) + d_j (T_{f_j} + T_{a_j})\right). \tag{26}$$

Let us consider the terms appearing in Eqs. (23), (24) and (25),

$$\underbrace{\frac{j}{j+d_j} (T_{f_j} T_{g_j} + T_{f_j} T_{a_j}) + d_j (T_{g_j} + T_{a_j})}_{(23)} + \underbrace{jd_j^2}_{(25)} + \underbrace{jd_j (T_{f_j} + T_{g_j}) + d_j (T_{f_j} + T_{a_j})}_{(24)}.$$

We have $d_j T_{g_j} \leq jd_j T_{g_j}$ and, since $T_{f_j} \leq T_{g_j}$, we get $jd_j (T_{f_j} + T_{g_j}) \in \mathcal{O}(jd_j T_{g_j})$. By Eqs. (23), (24) and (25) the expected cost $C_{Ev_j} = \sum_{i=1}^{d_j} C_{Ev_{ji}}$ of evaluation at the j th step is in

$$C_{Ev_j} \in \mathcal{O}\left(\frac{j}{j+d_j} T_{a_j} T_{f_j} + \frac{j}{j+d_j} T_{f_j} T_{g_j} + jd_j T_{g_j} + (j+d_j)(T_{f_j} + T_{a_j}) + jd_j^2\right). \tag{27}$$

Let C_{B_j} be the expected cost of BDP at the j th step. Then $C_{B_j} = \sum_{i=1}^{d_j} C_{B_{ji}} = \sum_{i=1}^{d_j} \mathcal{O}(\lceil ev_{j,i-1} \rceil d_{ji}^3)$. First, we consider

$$\sum_{i=1}^{d_j-1} \lceil ev_{j,i-1} \rceil d_{ji}^3 \leq d_j^3 \left(d_j + \frac{j}{j+d_j} T_{f_j}\right) \leq d_j^4 + jd_j^2 T_{f_j}.$$

Hence

$$C_{B_j} \in \mathcal{O}\left(d_j^4 + jd_j^2 T_{f_j}\right). \tag{28}$$

Let C_{V_j} be the expected cost of solving linear systems (in sparse interpolation) at the j th step. Then $C_{V_j} = \sum_{i=1}^{d_j} C_{V_{ji}} = \sum_{i=1}^{d_j} \mathcal{O}\left(T_{f_{j,i-1}}^2 r_{j,i-1}^2\right)$. We consider

$$\begin{aligned} \sum_{i=0}^{d_j-1} T_{f_j}^2 t_{j_i}^2 &= \sum_{i=0}^{d_j-1} \left(t_{f_j} \binom{j+d_{ji}}{j} \frac{j-1}{j-1+d_{ji}} \right)^2 \\ &= \sum_{i=0}^{d_j-1} \left(t_{f_j} \frac{j-1}{j-1+d_{ji}} \frac{j+d_{ji}}{j} \binom{j-1+d_{ji}}{j-1} \right)^2 \\ &\leq t_{f_j}^2 \sum_{i=0}^{d_j} \binom{j-1+d_{ji}}{j-1}^2 \leq t_{f_j}^2 \left(\sum_{i=0}^{d_j} \binom{j-1+d_{ji}}{j-1} \right)^2 \\ &= t_{f_j}^2 \binom{j+d_j}{j}^2 = T_{f_j}^2. \end{aligned}$$

Hence, the expected cost C_{V_j} is in

$$C_{V_j} \in \mathcal{O} \left(T_{f_j}^2 \right). \tag{29}$$

Let the expected cost of multiplication and division at the j th step be C_{D_j} and C_{M_j} resp. Then $C_{M_j} = \sum_{i=1}^{d_j} C_{M_{ji}} = \sum_{i=1}^{d_j} \mathcal{O} \left(t_{f_j} t_{g_j} \binom{j+d_j}{j} \binom{j+d_{ji}}{j} \right)$, and similarly for C_{D_j} . Note that

$$\begin{aligned} \sum_{i=1}^{d_j-1} t_{f_j} t_{g_j} \binom{j+d_j}{j} \binom{j+d_{ji}}{j} &= t_{f_j} t_{g_j} \binom{j+d_j}{j} \sum_{i=1}^{d_j-1} \binom{j-1+d_{ji}}{j-1} \\ &\leq t_{g_j} t_{f_j} \binom{j+d_j}{j}^2 = T_{f_j} T_{g_j}. \end{aligned}$$

So, the expected cost C_{M_j} of sparse multiplication and C_{D_j} of sparse division (in sparse interpolation) at the j th step is

$$C_{M_j} \in \mathcal{O} \left(T_{f_j} T_{g_j} \right) \text{ and } C_{D_j} \in \mathcal{O} \left(T_{f_j} T_{g_j} \right). \tag{30}$$

Let C_{U_j} be the cost of updating the factors at the j th step. Then $C_{U_j} = \sum_{i=1}^{d_j} C_{U_{ji}} = \sum_{i=1}^{d_j} \mathcal{O} \left(i(t_{f_j} + t_{g_j}) \binom{j+d_{ji}}{j} \right)$. We have

$$\begin{aligned} \sum_{i=1}^{d_j} i t_{g_j} \binom{j+d_{ji}}{j} &= t_{g_j} \sum_{i=1}^{d_j} i \binom{j+d_{ji}}{j} = t_{g_j} \frac{d_j(j+d_j+1)}{(j+1)(j+2)} \binom{j+d_j}{j} \\ &\leq \left(\frac{d_j(j+1) + d_j^2}{j^2} \right) t_{g_j} \binom{j+d_j}{j} = \left(\frac{d_j(j+1) + d_j^2}{j^2} \right) T_{g_j} \end{aligned}$$

Since $T_{f_j} \leq T_{g_j}$, we get

$$C_{U_j} \in \mathcal{O} \left(\frac{d_j}{j} T_{g_j} + \frac{d_j^2}{j^2} T_{g_j} \right). \tag{31}$$

Let C_{Er_j} be the cost of updating error at the j th step. Then $C_{Er_j} = \sum_{i=1}^{d_j} C_{Er_{ji}} = \sum_{i=1}^{d_j} \mathcal{O} \left((1 + \frac{d_j}{j})^2 T_{f_j} T_{g_j} \right)$ is in (assuming $d_j^3 > j^2$)

$$C_{Er_j} \in \mathcal{O} \left(\frac{d_j^3}{j^2} T_{f_j} T_{g_j} \right). \tag{32}$$

According to equations (27) to (32), we shall consider the dominating terms

$$\underbrace{\frac{j}{j+d_j}T_{a_j}T_{f_j} + \frac{j}{j+d_j}T_{f_j}T_{g_j} + jd_jT_{g_j} + d_j(T_{f_j} + T_{a_j}) + jd_j^2}_{C_{Evj}} + \underbrace{d_j^4 + jd_j^2T_{f_j}}_{C_{Bj}} + \underbrace{T_{f_j}^2}_{C_{Vj}} + \underbrace{T_{f_j}T_{g_j}}_{C_{Mj} \text{ and } C_{Dj}} + \underbrace{\left(\frac{d_j}{j} + \frac{d_j^2}{j^2}\right)T_{g_j}}_{C_{Uj}} + \underbrace{\frac{d_j^3}{j^2}T_{f_j}T_{g_j}}_{C_{Erj}}.$$

The terms $T_{f_j}^2$, $\frac{j}{j+d_j}T_{f_j}T_{g_j}$, $\left(\frac{d_j}{j} + \frac{d_j^2}{j^2}\right)T_{g_j}$, $T_{f_j}T_{g_j}$ will be dominated by the term $(d_j^3/j^2)T_{f_j}T_{g_j}$. The term jd_j^2 is dominated by $jd_j^2T_{f_j}$. Hence the expected complexity at the j th step is in

$$\mathcal{O}\left(\underbrace{\frac{j}{j+d_j}T_{a_j}T_{f_j} + jd_jT_{g_j} + d_j(T_{a_j} + T_{f_j})}_{C_{Evj}} + \underbrace{d_j^4 + jd_j^2T_{f_j}}_{C_{Bj}} + \underbrace{(d_j^3/j^2)T_{f_j}T_{g_j}}_{C_{Erj}}\right)$$

Let $\mathcal{J} = \{j \in \mathbb{N} \mid \max\{t_a, t_f, t_g\} \leq 1/(n^{-j+d})\}$. Then as it was explained in Section 4.1 we expect $T_{f_j}, T_{g_j}, T_{a_j}$ to be very close to T_f, T_g, T_a respectively for $j \in \mathcal{J}$. Then

$$\sum_{j=3}^n T_{a_j}T_{f_j} \in \Omega(|\mathcal{J}|T_aT_f).$$

According to Remark 15, in the sparse examples $|\mathcal{J}| \in \mathcal{O}(n)$. Then

$$\sum_{j=3}^n \frac{j}{j+d_j}T_{a_j}T_{f_j} < \sum_{j=3}^n \frac{j}{d_j}T_{a_j}T_{f_j} < \frac{n}{d} \sum_{j=3}^n T_{a_j}T_{f_j} \in \mathcal{O}\left(\frac{n^2}{d}T_aT_f\right).$$

On the other hand we have $\sum_{j=3}^n jd_jT_{g_j} \leq dT_g \sum_{j=3}^n j \in \mathcal{O}(n^2dT_g)$ and $\sum_{j=3}^n d_j(T_{a_j} + T_{f_j}) \leq (T_a + T_f) \sum_{j=3}^n d_j \leq nd(T_a + T_f)$. Also, for the error we have $\sum_{j=3}^n \frac{d_j^3}{j^2}T_{f_j}T_{g_j} < d^3T_fT_g \sum_{j=3}^n \frac{1}{j^2} < d^3T_fT_g$. We remark that if we use the weak Sparse Hensel assumption $\text{Supp}(\sigma_i) \subset \text{Supp}(\sigma_0)$ in Step 10 of Algorithm 5 we would instead obtain $nd^3T_fT_g$ for the error cost here. So assuming that the inputs are sparse by running the index j from 3 to n , the expected complexity of MTSHL is in

$$\mathcal{O}\left(\underbrace{\frac{n^2}{d}T_aT_f + n^2dT_g + nd(T_a + T_f)}_{\text{Evaluation}} + \underbrace{nd^4 + n^2d^2T_f}_{\text{BDP}} + \underbrace{d^3T_fT_g}_{\text{Er}}\right)$$

Since $T_f \leq T_g$ then the expected complexity is in

$$\begin{aligned} &\mathcal{O}\left(\frac{n^2}{d}T_aT_f + n^2dT_g + nd(T_a + T_g) + nd^4 + n^2d^2T_g + d^3T_fT_g\right) \\ &= \mathcal{O}\left(\frac{n^2}{d}T_aT_f + ndT_a + n^2d^2T_g + nd^4 + d^3T_fT_g\right) \end{aligned} \tag{33}$$

Finally we consider the failure probability of MTSHL. According to Lemma 1

$$\text{Pr}[\text{Supp}(f_{j,i+1}) \not\subseteq \text{Supp}(f_{ji})] \leq T_{f_{j,i+1}} \frac{d_{ji}}{p - d_{ji} + 1} \leq T_{f_j} \frac{d - i}{p - 2d + 1}.$$

Then the probability that one of the assumptions of Step 10 at the j th step is false is $\leq \sum_{i=0}^{d_j-1} T_{f_{j,i+1}} \frac{d_{ji}}{p-d_{ji}+1} \leq \frac{d^2}{2(p-2d+1)} T_f$. Hence throughout the whole MHL process the probability of failure of MHL because of a false assumption at Step 10 is $\leq \frac{(n-2)d^2}{2(p-2d+1)} T_f$.

Assuming $\text{Supp}(\sigma_i) \subseteq \text{Supp}(\sigma_{i-1})$, Proposition 3 says that the probability that Algorithm 4 fails at Step 5 and Step 10 is $< \frac{d^2 T_f (d + \frac{1}{2}) T_f + d^2}{p-1}$. Now throughout the whole MHL process Algorithm 4 is called $< (n-2)d$ times hence the probability of failure because of a failure in Algorithm 4 at Step 5 and Step 10 is $< \frac{(n-2)d^2 T_f (d + \frac{1}{2}) T_f + d^2}{p-1}$. Thus we proved that with the probability of failure

$$< (n-2)d^2 T_f \frac{d^2 + (d+1)T_f}{p-2d+1},$$

the expected complexity of MHL to recover the factors f, g via MTSHL algorithm is in

$$O\left(\frac{n^2}{d} T_f T_a + n d T_a + n^2 d^2 T_g + n d^4 + d^3 T_f T_g\right).$$

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